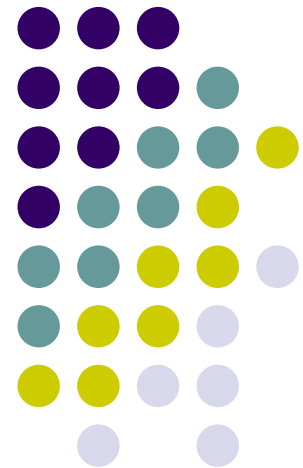


Chapter 12

Object Recognition

Yinghua He



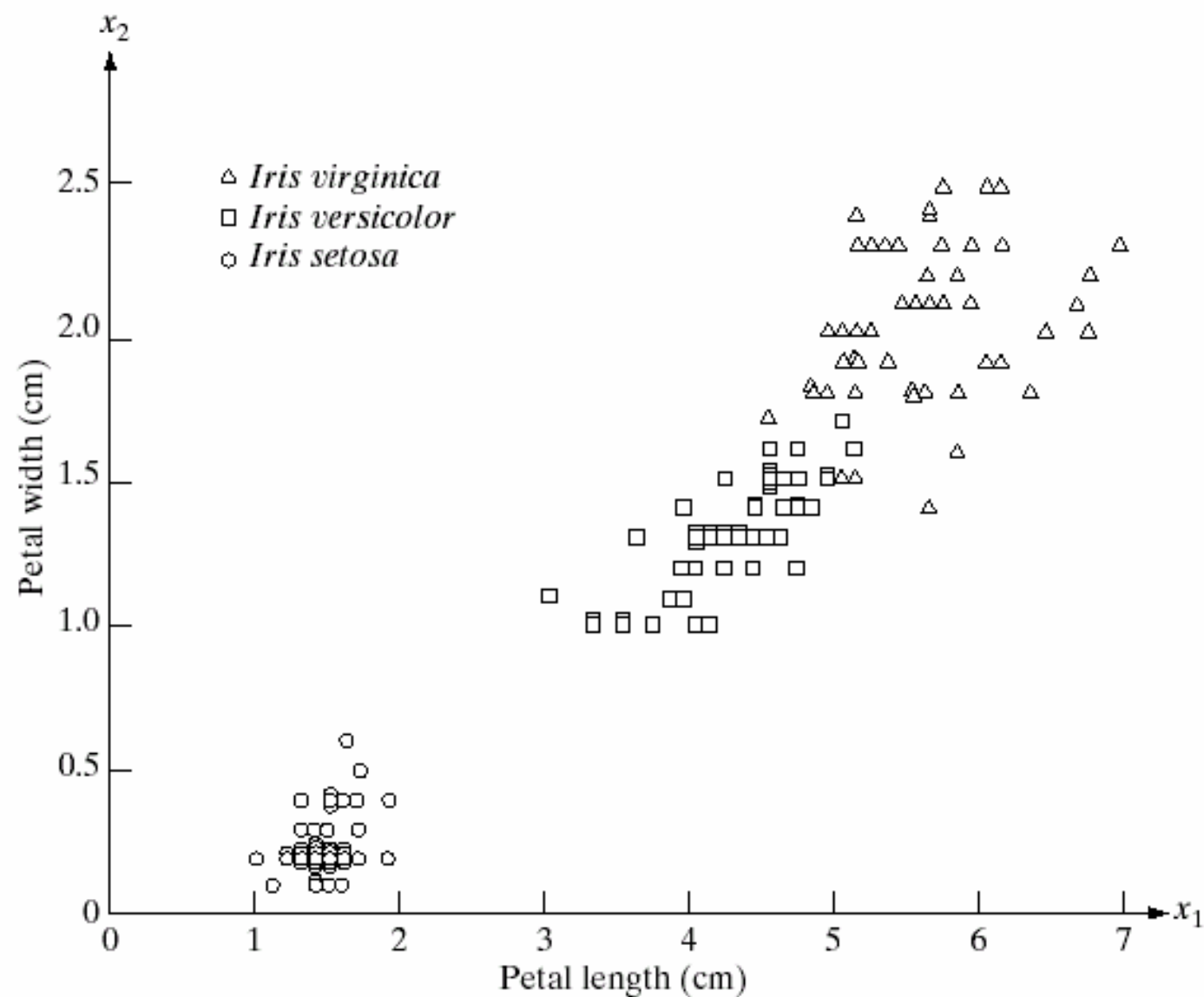


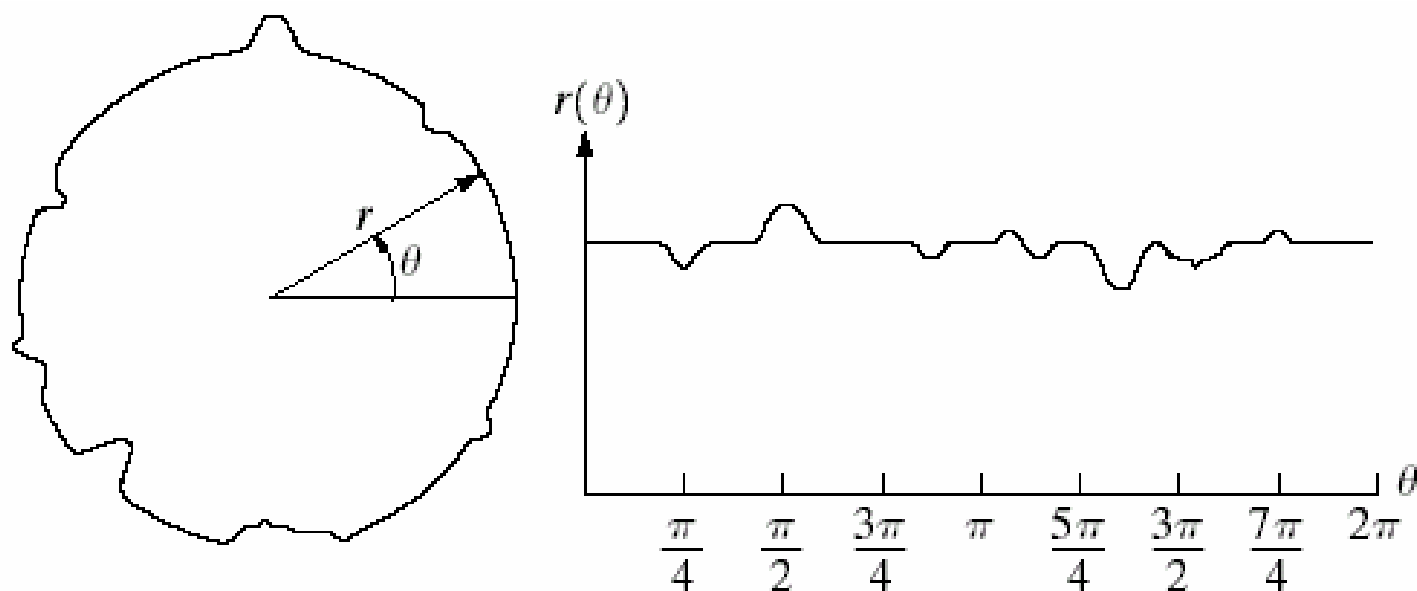
- Patterns and Pattern Classes
- Recognition Based on Decision-Theoretic Methods
- Structural Methods



FIGURE 12.1

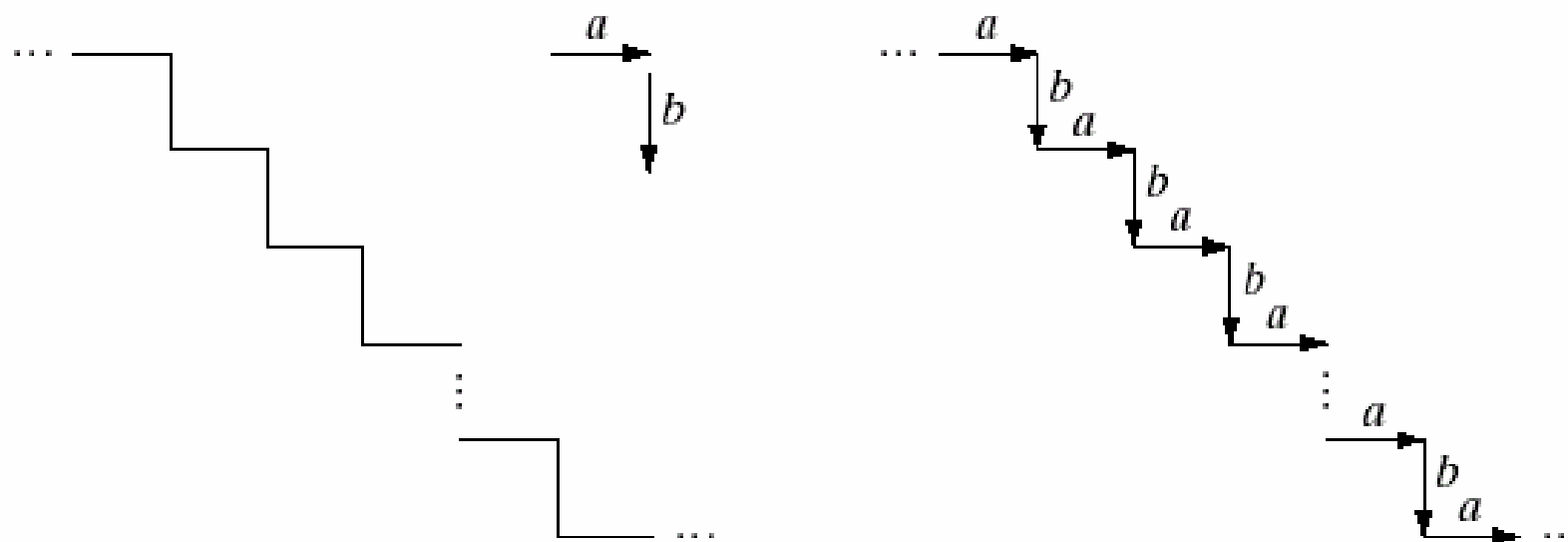
Three types of iris
flowers described
by two
measurements.





a b

FIGURE 12.2 A noisy object and its corresponding signature.



a b

FIGURE 12.3 (a) Staircase structure. (b) Structure coded in terms of the primitives a and b to yield the string description $\dots ababab \dots$.



FIGURE 12.4
Satellite image of
a heavily built
downtown area
(Washington,
D.C.) and
surrounding
residential areas.
(Courtesy of
NASA.)

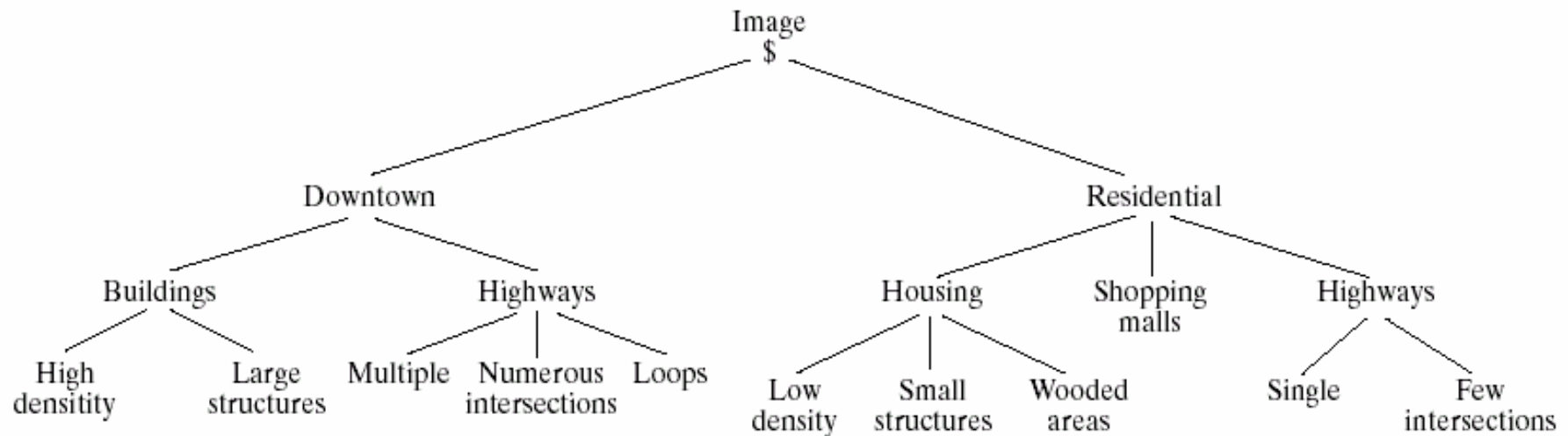
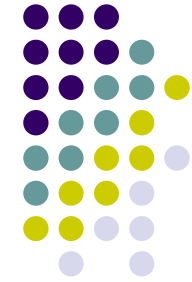


FIGURE 12.5 A tree description of the image in Fig. 12.4.



- Patterns and Pattern Classes
- Recognition Based on Decision-Theoretic Methods
- Structural Methods



- Matching
- Optimum Statistical Classifiers



$$m_j = \frac{1}{N_j} \sum_{x \in \omega_j} x_j \quad j = 1, 2, \dots, W$$

$$D_j(x) = \|x - m_j\| \quad j = 1, 2, \dots, W$$

$$\begin{cases} x \in \omega_i, & d_i(x) \geq d_j(x) \\ x \in \omega_j, & d_i(x) < d_j(x) \end{cases}$$

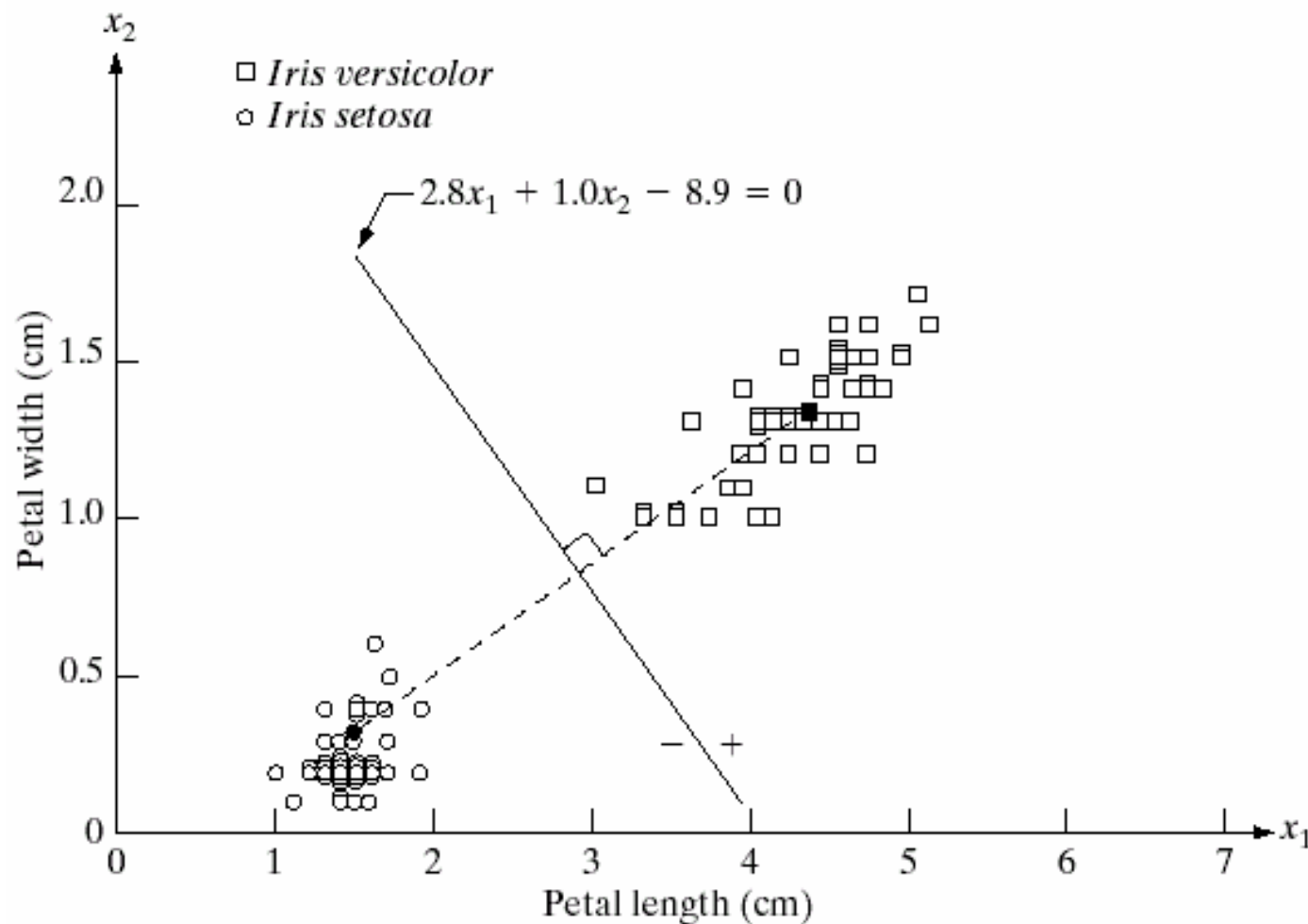


FIGURE 12.6
Decision boundary of minimum distance classifier for the classes of *Iris versicolor* and *Iris setosa*. The dark dot and square are the means.

$$\begin{aligned} d_1(x) &= x^T m_1 - \frac{1}{2} m_1^T m_1 \\ &= 4.3x_1 + 1.3x_2 - 10.1 \end{aligned}$$

$$\begin{aligned} d_2(x) &= x^T m_2 - \frac{1}{2} m_2^T m_2 \\ &= 1.5x_1 + 0.3x_2 - 1.17 \end{aligned}$$

$$\begin{aligned} d_{12}(x) &= d_1(x) - d_2(x) \\ &= 2.8x_1 + 1.0x_2 - 8.9 \end{aligned}$$



- Matching
- Optimum Statistical Classifiers



- The conditional average risk or loss in decision theory terminology.

$$r_j(x) = \sum_{k=1}^W L_{kj} p(\omega_k / x)$$

$$r_j(x) = \frac{1}{p(x)} \sum_{k=1}^W L_{kj} p(\omega_k / x) P(\omega_k)$$

$$r_j(x) = \sum_{k=1}^W L_{kj} p(x / \omega_k) P(\omega_k)$$



$$\sum_{k=1}^W L_{ki} p(x / \omega_k) P(\omega_k) < \sum_{k=1}^W L_{qj} p(x / \omega_q) P(\omega_q)$$

$$L_{ij} = 1 - \delta_{ij}$$

Where $\delta_{ij} = 1$ if $i=j$ and $\delta_{ij} = 0$ if $i \neq j$.

$$\begin{aligned} r_j(\mathbf{x}) &= \sum_{k=1}^W (1 - \delta_{kj}) p(\mathbf{x} / \omega_k) P(\omega_k) \\ &= p(\mathbf{x}) - p(\mathbf{x} / \omega_j) P(\omega_j). \end{aligned}$$



The Bayes classifier then assigns a pattern \mathbf{x} to class ω_i if, for all $j \neq i$,

$$p(\mathbf{x}) - p(\mathbf{x}/\omega_i)P(\omega_i) < p(\mathbf{x}) - p(\mathbf{x}/\omega_j)P(\omega_j) \quad (12.2-15)$$

or, equivalently, if

$$p(\mathbf{x}/\omega_i)P(\omega_i) > p(\mathbf{x}/\omega_j)P(\omega_j) \quad j = 1, 2, \dots, W; j \neq i. \quad (12.2-16)$$

With reference to the discussion leading to Eq. (12.2-1), we see that the Bayes classifier for a 0-1 loss function is nothing more than computation of decision functions of the form

$$d_j(\mathbf{x}) = p(\mathbf{x}/\omega_j)P(\omega_j) \quad j = 1, 2, \dots, W \quad (12.2-17)$$

$$d_j(x) = p(x/\omega_j)P(\omega_j)$$

$$= \frac{1}{\sqrt{2\pi}\sigma_j} e^{-\frac{(x-m_j)^2}{2\sigma_j^2}} P(\omega_j) \quad j = 1, 2$$



In the n -dimensional case, the Gaussian density of the vectors in the j th pattern class has the form

$$p(\mathbf{x}/\omega_j) = \frac{1}{(2\pi)^{n/2} |\mathbf{C}_j|^{1/2}} e^{-\frac{1}{2}(\mathbf{x}-\mathbf{m}_j)^T \mathbf{C}_j^{-1} (\mathbf{x}-\mathbf{m}_j)} \quad (12.2-19)$$

$$\mathbf{m}_j = E_j\{\mathbf{x}\}$$

and

$$\mathbf{C}_j = E_j\{(\mathbf{x} - \mathbf{m}_j)(\mathbf{x} - \mathbf{m}_j)^T\}$$



$$\mathbf{m}_j = \frac{1}{N_j} \sum_{\mathbf{x} \in \omega_j} \mathbf{x}$$

and

$$\mathbf{C}_j = \frac{1}{N_j} \sum_{\mathbf{x} \in \omega_j} \mathbf{x}\mathbf{x}^T - \mathbf{m}_j\mathbf{m}_j^T$$

$$\begin{aligned} d_j(\mathbf{x}) &= \ln[p(\mathbf{x}/\omega_j)P(\omega_j)] \\ &= \ln p(\mathbf{x}/\omega_j) + \ln P(\omega_j). \end{aligned}$$

$$d_j(\mathbf{x}) = \ln P(\omega_j) - \frac{n}{2} \ln 2\pi - \frac{1}{2} \ln |\mathbf{C}_j| - \frac{1}{2} [(\mathbf{x} - \mathbf{m}_j)^T \mathbf{C}_j^{-1} (\mathbf{x} - \mathbf{m}_j)]. \quad (12.2-25)$$

The term $(n/2) \ln 2\pi$ is the same for all classes, so it can be eliminated from Eq. (12.2-25), which then becomes

$$d_j(\mathbf{x}) = \ln P(\omega_j) - \frac{1}{2} \ln |\mathbf{C}_j| - \frac{1}{2} [(\mathbf{x} - \mathbf{m}_j)^T \mathbf{C}_j^{-1} (\mathbf{x} - \mathbf{m}_j)] \quad (12.2-26)$$



If all covariance matrices are equal, then $\mathbf{C}_j = \mathbf{C}$, for $j = 1, 2, \dots, W$. By expanding Eq. (12.2-26) and dropping all terms independent of j , we obtain

$$d_j(\mathbf{x}) = \ln P(\omega_j) + \mathbf{x}^T \mathbf{C}^{-1} \mathbf{m}_j - \frac{1}{2} \mathbf{m}_j^T \mathbf{C}^{-1} \mathbf{m}_j, \quad (12.2-27)$$

which are linear decision functions (*hyperplanes*) for $j = 1, 2, \dots, W$.

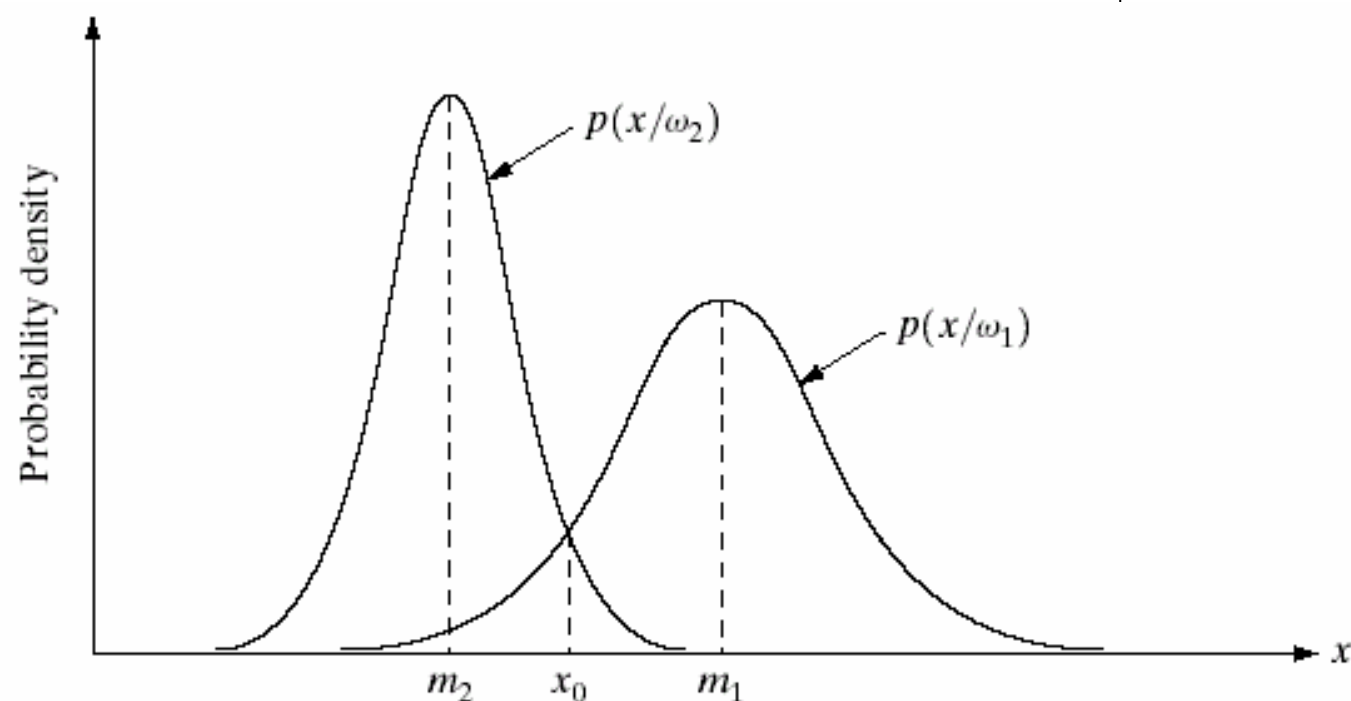
If, in addition, $\mathbf{C} = \mathbf{I}$, where \mathbf{I} is the identity matrix, and also $P(\omega_j) = 1/W$, for $j = 1, 2, \dots, W$, then

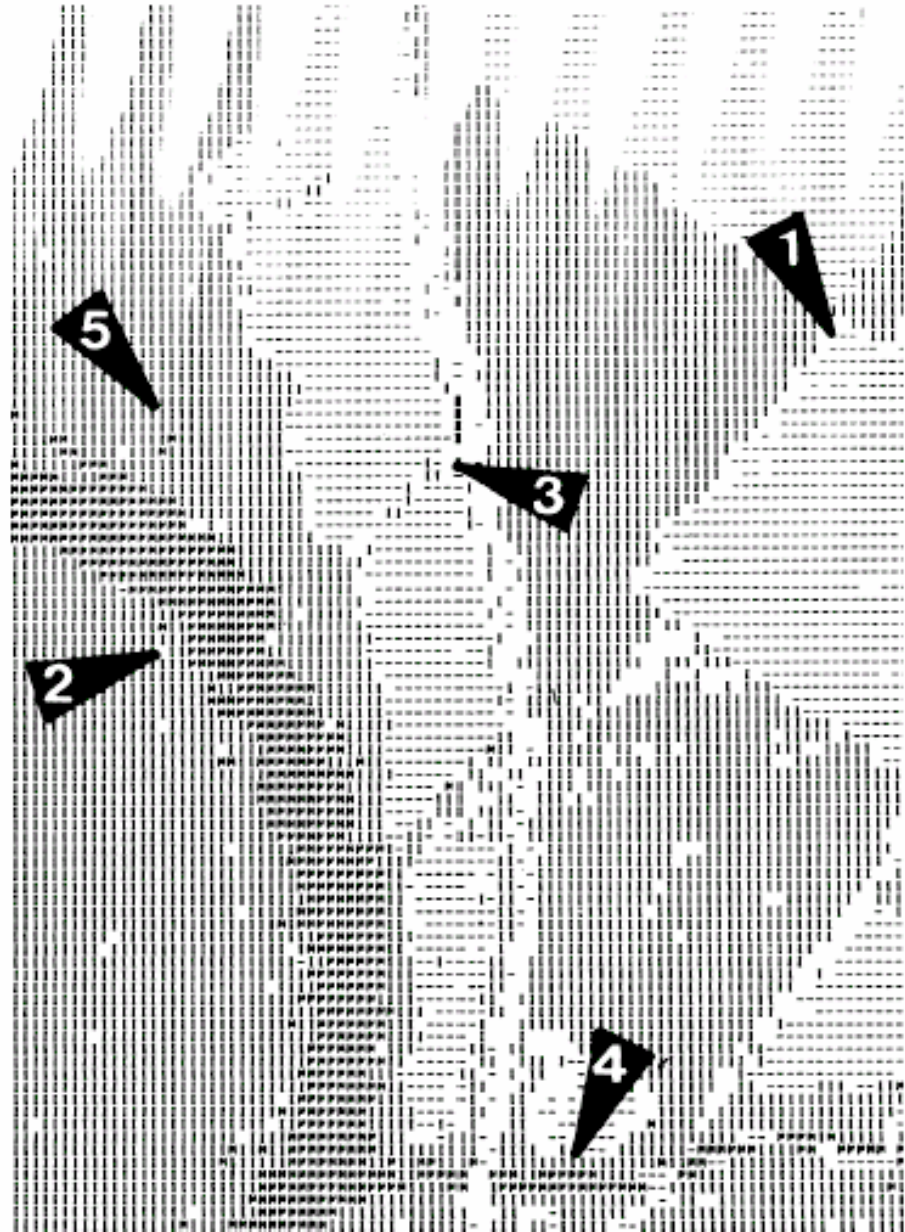
$$d_j(\mathbf{x}) = \mathbf{x}^T \mathbf{m}_j - \frac{1}{2} \mathbf{m}_j^T \mathbf{m}_j \quad j = 1, 2, \dots, W. \quad (12.2-28)$$



FIGURE 12.10

Probability density functions for two 1-D pattern classes. The point x_0 shown is the decision boundary if the two classes are equally likely to occur.





a b

FIGURE 12.13 (a) Multispectral image. (b) Printout of machine classification results using a Bayes classifier. (Courtesy of the Laboratory for Applications of Remote Sensing, Purdue University.)



- Patterns and Pattern Classes
- Recognition Based on Decision-Theoretic Methods
- Structural Methods



- Matching Shape Numbers
- String Matching



$$\begin{aligned} s_j(a) &= s_j(b) && \text{for } j = 4, 6, 8, \dots, k \\ s_j(a) &\neq s_j(b) && \text{for } j = k + 2, k + 4, \dots \end{aligned}$$

where s indicates shape number and the subscript indicates order. The *distance* between two shapes a and b is defined as the inverse of their degree of similarity:

$$D(a, b) = \frac{1}{k}. \quad (12.3-2)$$

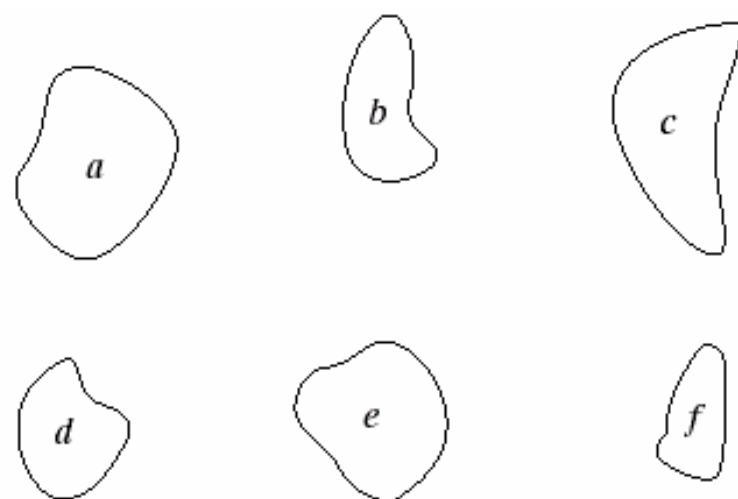


This distance satisfies the following properties:

$$D(a, b) \geq 0$$

$$D(a, b) = 0 \quad \text{iff } a = b$$

$$D(a, c) \leq \max[D(a, b), D(b, c)].$$



a
b c

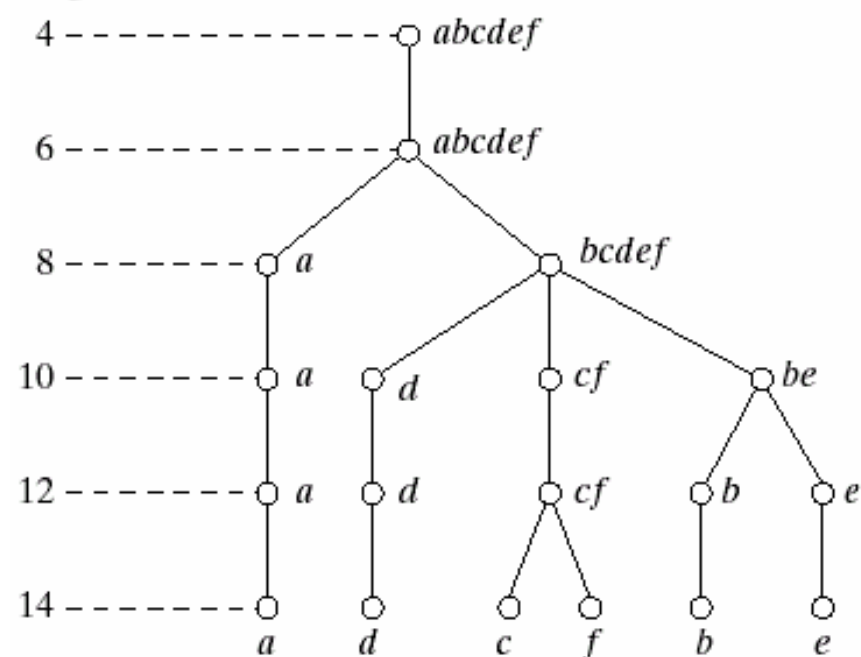
FIGURE 12.24

(a) Shapes.

(b) Hypothetical
similarity tree.

(c) Similarity
matrix. (Bribiesca
and Guzman.)

Degree



	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>
<i>a</i>	∞	6	6	6	6	6
<i>b</i>		∞	8	8	10	8
<i>c</i>			∞	8	8	12
<i>d</i>				∞	8	8
<i>e</i>					∞	8
<i>f</i>						∞



- Matching Shape Numbers
- String Matching



Suppose that two region boundaries, a and b , are coded into strings (see Section 11.5) denoted $a_1 a_2 \dots a_n$ and $b_1 b_2 \dots b_m$, respectively. Let α represent the number of matches between the two strings, where a match occurs in the k th position if $a_k = b_k$. The number of symbols that do not match is

$$\beta = \max(|a|, |b|) - \alpha \quad (12.3-4)$$

where $|\arg|$ is the length (number of symbols) in the string representation of the argument. It can be shown that $\beta = 0$ if and only if a and b are identical (see Problem 12.21).

A simple measure of similarity between a and b is the ratio

$$R = \frac{\alpha}{\beta} = \frac{\alpha}{\max(|a|, |b|) - \alpha}. \quad (12.3-5)$$



a	b
c	d
e	f
g	

FIGURE 12.25 (a) and (b) Sample boundaries of two different object classes; (c) and (d) their corresponding polygonal approximations; (e)–(g) tabulations of R . (Sze and Yang.)

R	1.a	1.b	1.c	1.d	1.e	1.f
1.a	∞					
1.b	16.0	∞				
1.c	9.6	26.3	∞			
1.d	5.1	8.1	10.3	∞		
1.e	4.7	7.2	10.3	14.2	∞	
1.f	4.7	7.2	10.3	8.4	23.7	∞

R	2.a	2.b	2.c	2.d	2.e	2.f
2.a	∞					
2.b	33.5	∞				
2.c	4.8	5.8	∞			
2.d	3.6	4.2	19.3	∞		
2.e	2.8	3.3	9.2	18.3	∞	
2.f	2.6	3.0	7.7	13.5	27.0	∞

R	1.a	1.b	1.c	1.d	1.e	1.f
2.a	1.24	1.50	1.32	1.47	1.55	1.48
2.b	1.18	1.43	1.32	1.47	1.55	1.48
2.c	1.02	1.18	1.19	1.32	1.39	1.48
2.d	1.02	1.18	1.19	1.32	1.29	1.40
2.e	0.93	1.07	1.08	1.19	1.24	1.25
2.f	0.89	1.02	1.02	1.24	1.22	1.18

The end

