Feature Selection for Monotonic Classification

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***Abstract*—Monotonic classification is a kind of special task in machine learning and pattern recognition. Monotonicity constraints between features and decision should be taken into account in these tasks. However, most existing techniques are not able to discover and represent the ordinal structures in monotonic datasets. Thus, they are inapplicable to monotonic classification. Feature selection has been proven effective in improving classification performance and avoiding overfitting. To the best of our knowledge, no technique has been specially designed to select features in monotonic classification until now. In this paper, we introduce a function, which is called rank mutual information, to evaluate monotonic consistency between features and decision in monotonic tasks. This function combines the advantages of dominance rough sets in reflecting ordinal structures and mutual information in terms of robustness. Then, rank mutual information is integrated with the search strategy of min-redundancy and max-relevance to compute optimal subsets of features. A collection of numerical experiments are given to show the effectiveness of the proposed technique.**

***Index Terms*—Feature selection, fuzzy ordinal set, monotonic classification, rank mutual information (RMI).**

I. Introduction

CLASSIFICATION tasks can be divided into two groups: nominal classification and ordinal classification. As to nominal classification [52], [53], [56], there is no ordinal structure among different decision values. For example, we recognize different diseases according to the symptoms of patients. However, as to ordinal classification (which is also called ordinal regression) [1], [3], [4], [55], we should consider the ordinal relationship between different class labels, such as the severity levels of a disease {slight, medium, and severe}. Furthermore, monotonic classification is a class of special ordinal classification tasks, where the decision values are ordinal and discrete, and there are monotonicity constraints between features and decision classes where $x \leq x' \Rightarrow f(x) \leq f(x')$ [1]. Monotonic classification is a kind of common tasks in medical analysis, social, and behavioral sciences [2]. Such problems have attracted increasing attention from the domains of machine learning and intelligence data analysis [3]–[5].

The previous work on monotonic classification can be roughly divided into two groups. One attempts to construct a theoretic framework for monotonic classification, including the dominance rough set model [6]–[10] and the ordinal entropy model [11], whereas the other is dedicated to developing algorithms for learning decision models from samples [12]–[15]. In 1999, Greco *et al*. first introduced dominance relations into rough sets and proposed the model of dominance rough sets. This model built a formal framework to study monotonic classification. After that, this model was extensively discussed and generalized. On the other hand, Ben-David extended the classical decision tree algorithm to monotonic classification in 1995. Since then, a collection of decision tree algorithms have been developed for this problem [16]–[20]. In addition, Ben-David also extended the nearest neighbor classifier to monotonic tasks and designed an ordinal learning model (OLM) [22]. In 2003, Cao-Van introduced ordinal stochastic dominance learner (OSDL) based on associated cumulative distribution. In 2008, Lievens *et al*. presented a probabilistic framework that served as the base of instance-based algorithms to solve the supervised ranking problems [23]. In addition, in 2008, Duivesteijn and Feelders proposed a modified nearest neighbor algorithm for the construction of monotone classifiers from data by monotonizing training data. The relabeled data were subsequently used as the training set by a modified nearest neighbor algorithm [14]. Recently, support vector machines and other kernel machines have also been adapted to such tasks [24], [25]. Based on the aforementioned survey, we can see that monotonic classification is becoming a hot topic in machine learning.

As we know, feature selection plays an important role in improving classification performance and speeding up training [26], [27]. A great number of feature selection algorithms have been designed for classification learning until now. The main differences between these techniques lie in the metrics that are used to evaluate the quality of candidate features and search strategies to find optimal solutions in terms of the used metric. Mutual information (MI) [28]–[31], dependence [32]–[36], consistency [37], [38], [54], distance [39], and classification margin [40]–[42] were introduced or developed as metrics of feature quality in feature selection. In addition, after defining the optimization objectives, a search strategy should be designed to find the optimal solution. Greedy search, heuristic search, branch and bound, genetic optimization, and

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other intelligent search algorithms are used in feature selection [43]–[45].

Although a lot of algorithms were developed for feature selection, little effort has yet to be devoted to design feature selection algorithms for monotonic classification. As different consistency assumptions are taken for monotonic classification and nominal classification, the feature evaluation functions that are developed for nominal classification cannot be directly applied to monotonic classification because the metrics in nominal classification do not consider the monotonicity constraints. As a result, a feature producing a large value of feature quality may not be useful for enhancing the monotonicity of monotone tasks. Thus, new evaluation functions should be developed for this kind of special tasks. Kamishima and Akaho [46] and Baccianella *et al*. [47] designed a feature selection procedure for ordinal classification, respectively. However, the feature evaluation functions that are used in these algorithms do not reflect the monotonicity between features and decision. Therefore, they are not applicable to monotonic classification. In 2006, Lee *et al*. improved the dependence function that is defined in dominance rough sets and used it to attribute reduction for monotonic classification. In addition, Xu *et al*. gave another framework of attribute reduction based on evidence theory [48]. Although dependence that is defined in dominance rough sets can reflect the ordinal structures in monotonic data, dominance rough sets are very sensitive to noisy information. The evaluation function may vary quite a bit if there are several inconsistent samples in the datasets [49]. We should design a robust metric of feature quality, which can also discover ordinal structures of monotone tasks.

In 2010, Hu *et al*. introduced two new attribute metrics, i.e., rank mutual information (RMI) and fuzzy rank mutual information (FRMI), to compute the monotonic consistency between two random variables [11]. However, they did not discuss the issue of feature selection for monotonic classification. In addition, no experimental analysis was described to show the effectiveness of the proposed measure. As we know, MI in Shannon's information theory is widely used in feature evaluation for nominal classification tasks and its effectiveness has been verified in applications [26]–[30], [50]. Naturally, we also want RMI and FRMI to be powerful in evaluating and selecting monotonic features. Therefore, in this paper, we first discuss the properties of rank entropy and RMI in evaluating features, and then we design feature selection algorithms based on these metrics and conduct experiments to test them. We integrate RMI with the search strategy of min-redundancy and max-relevance (mRMR). Thus, an effective algorithm for monotonic feature selection is constructed. Some numerical experiments are presented to show the effectiveness of the proposed technique.

The rest of this paper is organized as follows. First, we present the preliminaries on monotonic classification and dominance rough sets in Section II; then, we show the definitions of RMI and FRMI and discuss their properties in Section III. Section IV gives the feature selection algorithms for monotonic classification. Numerical experiments are presented in Section V. Finally, conclusions and future work are given in Section VI.

II. Preliminaries on Monotonic Classification

The following definitions can be found in [6] and [7].

Definition 1: Let $\langle U, A, D\rangle$ be a set of classification dataset, where $U = \{x_i\}_{i=1}^{n}$ is the set of samples, $A = \{a_j\}_{j=1}^{m}$ is the set of attributes, and D is the decision of the samples. The value domain of D is $\{d_1, d_2, \ldots, d_K\}$. If D is nominal, we say $\langle U, A, D\rangle$ is a nominal classification task. If there are ordinal structures between the values of decision, $d_1 < d_2 < \cdots < d_K$, we say $\langle U, A, D\rangle$ is an ordinal classification task. Let $v(x, A)$ denote the value vector of sample x on A, and let f be the decision function. If $\forall x \in U, v(x, A) \preceq v(x', A)$, we have $f(x) \leq f(x')$, and then, we say $\langle U, A, D\rangle$ is a monotonic classification task.

In this paper, we focus on monotonic classification tasks.

Definition 2: Given a monotonic classification task $\langle U, A, D\rangle$, $B \subseteq A$, we associate ordinal relations with the attributes and decision as

1) $R_B^{\leq} = \{(x_i, x_j) | v(x_i, a_l) \leq v(x_j, a_l), \forall a_l \in B\}$;
2) $R_D^{\leq} = \{(x_i, x_j) \in U \times U | v(x_i, D) \leq v(x_j, D)\}$.

Definition 3: Given $\langle U, A, D\rangle$, $B \subseteq A$. $\forall x_i \in U$, we define the following subsets of samples:

1) $[x_i]_B^{\leq} = \{x_j \in U | (x_i, x_j) \in R_B^{\leq}\}$;
2) $[x_i]_D^{\leq} = \{x_j \in U | (x_i, x_j) \in R_D^{\leq}\}$;

which are called B-dominating set and D-dominating set of x_i, respectively.

Given $\langle U, A, D\rangle$, $B \subseteq A$, $x_i, x_j \in U$, the following conclusions hold:

1) $R_A^{\leq} \subseteq R_B^{\leq}$;
2) $[x_i]_A^{\leq} \subseteq [x_i]_B^{\leq}$; and
3) if $x_j \in [x_i]_B^{\leq}$, then $[x_j]_B^{\leq} \subseteq [x_i]_B^{\leq}$, and $[x_i]_B^{\leq} = \cup\{[x_j]_B^{\leq} | x_j \in [x_i]_B^{\leq}\}$.

Definition 4: Given $\langle U, A, D\rangle$, $B \subseteq A$, $X \subseteq U$. The lower and upper approximations of X in terms of B are defined as follows:

1) $\underline{R_B^{\leq}} X = \{x \in U | [x]_B^{\leq} \subseteq X\}$;
2) $\overline{R_B^{\leq}} X = \{x \in U | [x]_B^{\geq} \cap X \neq \emptyset\}$.

It is easy to obtain the following conclusions:

1) $\underline{R_B^{\leq}} X \subseteq X \subseteq \overline{R_B^{\leq}} X$;
2) $\underline{R_B^{\leq}} U \subseteq U$, $\overline{R_B^{\leq}} \emptyset \subseteq \emptyset$;
3) $\underline{R_B^{\leq}} \sim X = \sim \underline{R_B^{\leq}} X$, $\overline{R_B^{\leq}} \sim X = \sim \overline{R_B^{\leq}} X$;
4) if $X \subseteq Y \subseteq U$, $\underline{R_B^{\leq}} X \subseteq \underline{R_B^{\leq}} Y$, $\overline{R_B^{\leq}} X \subseteq \overline{R_B^{\leq}} Y$.

Definition 5: Given $\langle U, A, D\rangle$, $B \subseteq A$. d_i is the ith class, the boundary of d_i are defined as

$$BN(d_i^{\leq}) = \overline{R_B^{\leq}} d_i^{\leq} - \underline{R_B^{\leq}} d_i^{\leq}. \tag{1}$$

Definition 6: Given $\langle U, A, D\rangle$, $B \subseteq A$, and $\{d_1, d_2, \ldots, d_K\}$ is the value domain of D. The boundary of classification D is defined as

$$BN(D^{\leq}) = \bigcup_{i=1}^{K} BN(d_i^{\leq}). \tag{2}$$

Similarly, we can also define $BN(d_i^{\geq})$ and $BN(D^{\geq})$. It is easy to derive that $BN(d_i^{\leq}) = BN(d_{i+1}^{\geq})$ and $BN(D^{\geq}) = BN(D^{\leq})$. Moreover, we define $\underline{R_B} d_i = \underline{R_B^{\leq}} d_i^{\leq} \cap \underline{R_B^{\geq}} d_i^{\geq}$.

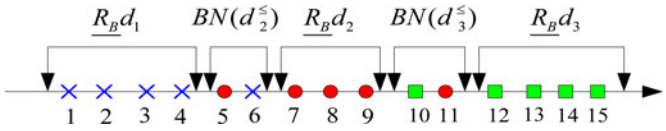

Fig. 1. Toy example of dominance rough sets.

Example 1: A set of objects is divided into three levels according to the attribute B, which is presented in Fig. 1, where $\times$, $\bullet$, and $\square$ stand for samples coming from classes 1, 2, and 3, respectively.

According to the aforesaid definitions, we obtain that $\underline{R_B}d_1 = \{x_1, x_2, x_3, x_4\}$, $BN(d_2^{\leq}) = \{x_5, x_6\}$, $\underline{R_B}d_2 = \{x_7, x_8, x_9\}$, $BN(d_2^{\leq}) = \{x_{10}, x_{11}\}$, and $\underline{R_B}d_3 = \{x_{12}, x_{13}, x_{14}, x_{15}\}$.

The samples in the boundary set are the source of difficulty of classification. They form the inconsistency of classification. We give a metric to evaluate the monotonic consistency as

$$\gamma_B(D) = \frac{|U - \cup_{i=1}^{K} BND_B(d_i)|}{|U|} \tag{3}$$

where $|X|$ is the number of the elements in X. We call this metric monotonic dependence of D on B. If $\gamma_B(D) = 1$, we say D is completely dependent on B. The dataset is monotonically consistent in this case. All the samples with better feature values also obtain better decision labels. However, most classification tasks are not consistent in real-world applications.

As to the task in *Example 1*, we have $\gamma_B(D) = |U - \{x_5, x_6\} \cup \{x_{10}, x_{11}\}|/|U| = 11/15$. Monotonic dependence characterizes the relevance between attributes and classification. However, this metric is sensitive to noisy samples. For example, we just change the decision of Sample 15 as class 1, then $BN(D^{\leq}) = \{x_5, \ldots, x_{14}\}$, and $\gamma_B(D) = |U - \{x_5, x_6\} \cup \{x_{10}, x_{11}\}|/|U| = 5/15$. As we know, the decisions are usually given by different persons in different contexts; there are many inconsistent decisions in data; therefore, a robust metric is desirable in this case.

Because of inconsistency, a sample with higher values of features does not necessarily obtain a better decision. However, we know that a sample with larger values of features should produce a better decision with a large probability [4], [5]. For applicability, stochastic monotonicity should be considered to describe monotonic classification tasks.

III. Monotonic Consistency Metric

There are several kinds of uncertainty in monotonic classification, such as randomicity, fuzziness, and inconstancy. The metric to evaluate quality of features should consider these problems. First, we introduce some definitions on rank entropy and RMI [11], which reflects the stochastic monotonicity between features and decision.

Definition 7: Let $U = \{x_1, x_2, \ldots, x_n\}$ and $x_i \in U$ and $R = \{r_{ij}\}_{n\times n}$ be an ordinal relation over U. The fuzzy ordinal set of x_i is formulated as $[x_i]_R^{\leq} = r_{i1}/x_1 + r_{i2}/x_2 + \ldots + r_{in}/x_n$, where r_{ij} is the degree of x_i worse than x_j. We have

$$\begin{cases} x_i > x_j, \ r_{ij} \in [0, 0.5) \\ x_i = x_j, \ r_{ij} = 0.5 \\ x_i < x_j, \ r_{ij} \in (0.5, 1]. \end{cases} \tag{4}$$

The fuzzy dominated set of x_i is a fuzzy set which dominates x_i, The membership r_{ij} reflects the magnitude of x_i worse than x_j.

If we define a cut operator on the aforementioned fuzzy ordinal set as $r_{ij} = 0$ if $r_{ij} < 0.5$; otherwise, $r_{ij} = 1$, then the fuzzy ordinal set becomes a crisp ordinal set, as shown in Fig. 2.

Definition 8: Let U be a set of objects and $R = \{r_{ij}\}_{n\times n}$ be an ordinal relation over U induced by $B \subseteq A$. $[x_i]_R^{\leq}$ is the fuzzy ordinal set associated with x_i. The fuzzy rank entropy of the system $\langle U, R\rangle$ is defined as

$$RH_R(U) = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_R^{\leq}|}{n} \tag{5}$$

where $|[x_i]_R^{\leq}| = \sum_j r_{ij}$ is the fuzzy cardinality of fuzzy set $[x_i]_R^{\leq}$.

$RH_R(U)$ is also written as $RH_B(U)$. As we know, $0 \leq |[x_i]_R^{\leq}| \leq n$; therefore, $0 \leq RH_R(U)$. In addition, assume that R_1 and R_2 are two fuzzy ordinal relations on U. If $R_1 \subseteq R_2$, we have $RH_{R_1}(U) \geq RH_{R_2}(U)$.

Definition 9: Given U, R and S are two fuzzy ordinal relations on U induced by attributes B_1 and B_2. $T = R \cap S$ is the relation induced by $B_1 \cup B_2$. That is to say $[x_i]_T^{\leq} = [x_i]_R^{\leq} \cap [x_i]_S^{\leq} = \min(r_{i1}, s_{i1})/x_1 + \min(r_{i2}, s_{i2})/x_2 + \ldots + \min(r_{in}, s_{in})/x_n$. The fuzzy rank joint entropy of R and S is defined as

$$RH_{R\cap S}(U) = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|}{n}. \tag{6}$$

It is easy to show that $RH_{R\cap S}(U) \geq 0$, $RH_{R\cap S}(U) \geq RH_R(U)$, and $RH_{R\cap S}(U) \geq RH_S(U)$. Moreover, if $R \subseteq S$, we have $RH_{R\cap S}(U) = RH_R(U)$. This analysis shows the joint entropy of two subsets of features is no smaller than the entropy of any of them. We can derive the following property. If $B \subseteq C$, we have $RH_B(U) \leq RH_C(U)$.

Definition 10: Given U, R and S are two fuzzy ordinal relations induced by attributes B_1 and B_2. By knowing B_2, the fuzzy rank conditional entropy of B_1 is defined as

$$RH_{R|S}(U) = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|}{|[x_i]_S^{\leq}|}. \tag{7}$$

As $|[x_i]_S^{\leq}| \geq |[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|$, $|[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|/|[x_i]_S^{\leq}| \leq 1$, then we can derive that $RH_{R|S}(U) \geq 0$. In addition, $|[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|/|[x_i]_S^{\leq}| \geq |[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|/n$; therefore, we have $RH_{R\cap S}(U) \geq RH_{R|S}(U)$.

Definition 11: Given U, R and S are two fuzzy ordinal relations induced by attributes B_1 and B_2. The FRMI of B_1 and B_2 is defined as

$$\text{RMI}_{R,S}(U) = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_R^{\leq}| \times |[x_i]_S^{\leq}|}{n \times |[x_i]_R^{\leq} \cap [x_i]_S^{\leq}|}. \tag{8}$$

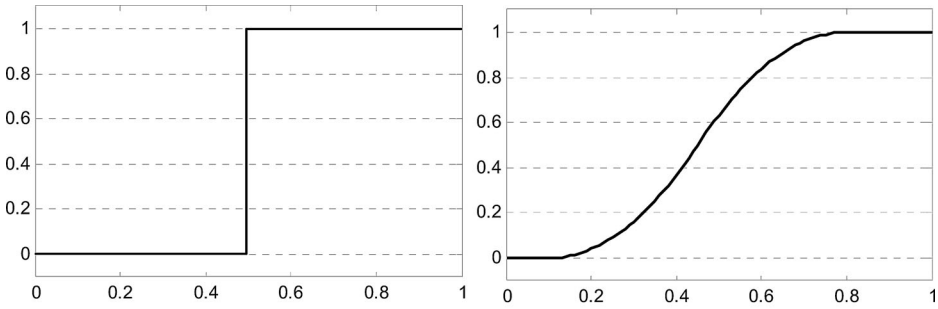

Fig. 2. Membership functions of ordinal sets.

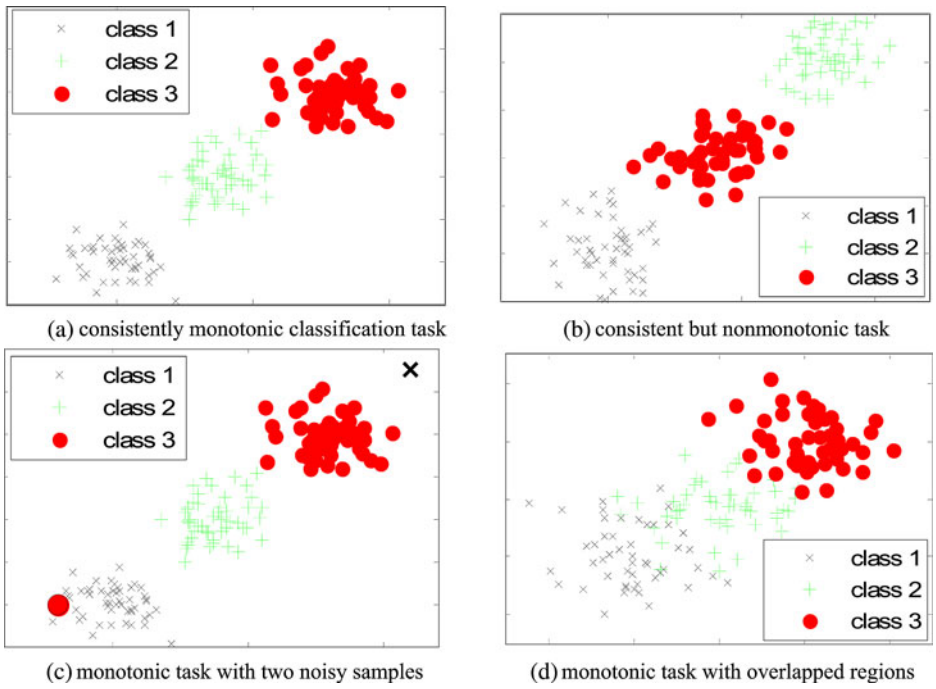

Fig. 3. (a)–(d) Toy examples of classification tasks in 2-D feature spaces.

Just like the relationship of information entropy, conditional entropy, and MI in Shannon's information theory, we also have

$$\mathrm{RMI}_{R,S}(U) = RH_R(U) - RH_{R|S}(U) \tag{9}$$

$$\mathrm{RMI}_{R,S}(U) = RH_S(U) - RH_{S|R}(U). \tag{10}$$

The aforesaid definitions give a point-wise way to define rank entropy, rank conditional entropy, and RMI, and the entropy of the universe can be understood as the expectation of samples' entropy. Take $x_i \in U$ as an example:

$$\begin{aligned}&\mathrm{RMI}_{R,S}(x_i)\\ &= -\log\left(|[x_i]_R^{\leqslant}| \times |[x_i]_S^{\leqslant}|\right) / \left(n \times |[x_i]_R^{\leqslant} \cap [x_i]_S^{\leqslant}|\right)\\ &= \log\left(n \times |[x_i]_R^{\leqslant} \cap [x_i]_S^{\leqslant}|\right) / \left(|[x_i]_R^{\leqslant}| \times |[x_i]_S^{\leqslant}|\right).\end{aligned}$$

For a set of given samples, n is a constant. Then, we just consider $\theta = |[x_i]_R^{\leqslant} \cap [x_i]_S^{\leqslant}| / \left(|[x_i]_R^{\leqslant}| \times |[x_i]_S^{\leqslant}|\right)$. θ can be understood as a similarity function of two fuzzy ordinal sets. If $[x_i]_R^{\leqslant} = [x_i]_S^{\leqslant}$, $\mathrm{RMI}_{R,S}(x_i) = -\log|[x_i]_S^{\leqslant}|/n = RH_S(x_i)$, which means the MI between R and S is equal to the rank entropy of R or S if they are the same.

Now, we show some toy examples in Fig. 3. There are four classification tasks that are described with two features. The first one is a monotonically consistent classification task, while the second one is consistent but nonmonotonic. The third one is monotonically consistent except two noisy samples, and the last one is a monotonic task with many inconsistent samples.

First, we consider (1) and (2). We compute the MI and RMI between features and decision of the two tasks. As to the first task, we obtain that MI = 0.928, and RMI = 0.723; as to the second task, MI = 0.952, and RMI = 0.472. We can see that MI does not vary much when the order of decision changes. It shows that MI is not sensitive to the ordinal structures of data. However, RMI decreases from 0.723 to 0.472. It tells us the features in the second task are not good for monotonic classification. Compared with MI, RMI reflects the ordinal structures of features.

Now, we consider (1) and (3). The dataset in (3) is generated from (1) by adding two noisy samples. We compute monotonic dependence and RMI. The monotonic dependence of decision on the two features is 1 as the task is consistently monotonic, as shown in Fig. 3(a). In this case, RMI = 0.723. However, if two noisy samples are added, which are shown in Fig. 3(c), monotonic dependence drops from 1 to 0.480, while RMI changes from 0.723 to 0.698. Obviously, the noisy samples have great impact on the monotonic dependence, while RMI is relatively robust. Fig. 3(d) presents a monotonic classification task. However, the class regions are overlapped. RMI = 0.665.

The aforementioned analysis shows RMI can reflect the ordinal structures between attributes and decision, while MI fails it. Moreover, compared with monotonic dependence, RMI is a robust metric to measure monotonic consistency.

IV. Feature Evaluation and Selection

In this section, we discuss the technique to evaluate quality of features for monotonic classification based on RMI. Then, we combine the evaluation function with mRMR [29] search strategy to select optimal features. Finally, two classification algorithms are introduced to validate selected features.

A. Feature Evaluation With Rank Mutual Information

In general classification learning, a set of learning samples is gathered and given to the learning algorithm. Let $\langle U, A, D\rangle$ be the dataset. As to a monotonic classification task, we assume the values of D have the following relation: $d_1 < d_2 < \ldots < d_k$. Given attribute $a \in A$, we introduce the following relation function [10]:

$$r_{ij}^{<} = \frac{1}{1 + e^{k(v(x_i,a)-v(x_j,a))}} \tag{11}$$

where $v(x_i, a)$ is the value of x_i on feature a, and k is a positive constant. This function is the well-known "logsig" transfer function that is used in neural networks. It is easy to see that $r_{ii}^{>} = r_{ii}^{<} = 0.5$, $r_{ij}^{<}$ approaches 1 if $v(x_j, a)$ is far larger than $v(x_i, a)$, and $r_{ij}^{<}$ approaches 0 if $v(x_j, a)$ is much smaller than $v(x_i, a)$. These results are consistent with our intuition: $r_{ij} = 0.5$ indicates that there is no difference between x_i and x_j, $r_{ij}^{<} = 1$ indicates that x_i is much smaller than x_j, and $r_{ij}^{<} = 0$ means x_i is much larger than x_j.

The relations that are computed with the aforementioned function are neither reflexive nor symmetric, but they are transitive, i.e., $r_{ii} \neq 1$, $r_{ij} \neq r_{ji}$, and $\min_y (R(x, y), R(y, z)) \leq R(x, z)$. The curves of the logsig function $f(x) = 1/(1 + \exp(-kx))$ under different values of k are shown in Fig. 4. Parameter k reflects user's preference and understanding of the words "larger" or "better." If k is very large, for example, $k = 100$, the fuzzy ordinal set can be understood as a fuzzy set of "slightly larger," while if k is small, for example, $k = 1$, the corresponding fuzzy set is a set of "significantly larger."

Now, we can get the fuzzy ordinal set which is larger than x_i in terms of attribute a, which is

$$[x_i]_a^{\leq} = r_{i1}/x_1 + r_{i2}/x_2 + \ldots + r_{in}/x_n. \tag{12}$$

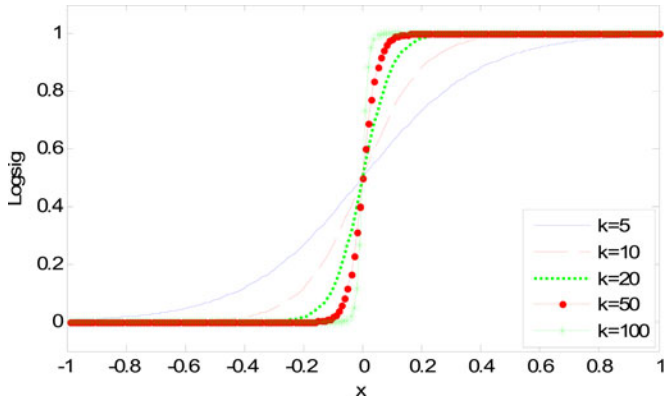

Fig. 4. Membership functions of fuzzy ordinal sets computed with logsig function under different parameter values.

Consider two features a_1 and a_2. If the fuzzy ordinal sets in terms of attributes a_1 and a_2 are $[x_i]_{a_1}^{\leq}$ and $[x_i]_{a_2}^{\leq}$, respectively, the fuzzy ordinal set in terms of $B = \{a_1, a_2\}$ is computed as $[x_i]_B^{\leq} = [x_i]_{a_1}^{\leq} \cap [x_i]_{a_2}^{\leq}$, where $\bigcap$ is a fuzzy intersection operator. Now, the RMI between a_1 and a_2 is calculated with

$$\text{RMI}_{a_1,a_2}(U) = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_{a_1}^{\leq}| \times |[x_i]_{a_2}^{\leq}|}{n \times |[x_i]_{a_1}^{\leq} \cap [x_i]_{a_2}^{\leq}|}. \tag{13}$$

Regarding features B and D, $\text{RMI}_{B,D}(U)$ reflects the monotonic consistency between B and D. We consider $\text{RMI}_{B,D}(U)$ as the significance of B in predicting D. For simplicity, $\text{RMI}_{B,D}(U)$ is also written as $\text{RMI}_{B,D}$ in the following.

Theorem 1: Given a monotonic classification dataset $\langle U, A, D\rangle$, $B \subseteq A$. If D is completely dependent on B, we have $\text{RMI}_{B,D} = RH_D(U)$.

Proof: If D is completely dependent on B, the monotonic classification is consistent in this case. That is to say, $[x_i]_B^{\leq} \subseteq [x_i]_D^{\leq}$. Thus, $\text{RMI}_{B,D} = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_B^{\leq}| \times |[x_i]_D^{\leq}|}{n \times |[x_i]_B^{\leq} \cap [x_i]_D^{\leq}|} = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_B^{\leq}| \times |[x_i]_D^{\leq}|}{n \times |[x_i]_B^{\leq}|} = -\sum_{i=1}^{n} \frac{1}{n} \log \frac{|[x_i]_D^{\leq}|}{n} = RH_D(U)$.

Definition 12: Given a monotonic classification dataset $\langle U, A, D\rangle$, $B \subseteq A$ and $a \in A - B$. The significance of a with respect to B is defined as $Sig(a, B, D) = \text{RMI}_{B\cup\{a\},D} - \text{RMI}_{B,D}$.

Corollary 1: Given a monotonic classification dataset $\langle U, A, D\rangle$, $B \subseteq A$. If D is completely dependent on B and $a \in A - B$, we have $Sig(a, B, D) = 0$.

Proof: If D is completely dependent on B, $[x_i]_B^{\leq} \subseteq [x_i]_D^{\leq}$. Let $C = B \cup \{a\}$. $[x_i]_C^{\leq} = [x_i]_B^{\leq} \cap [x_i]_a^{\leq}$; thus, $[x_i]_C^{\leq} \subseteq [x_i]_B^{\leq} \subseteq [x_i]_D^{\leq}$. $\text{RMI}_{B\cup\{a\},D} = RH_D(U)$ and $\text{RMI}_{B,D} = RH_D(U)$. $\text{RMI}_{B\cup\{a\},D} - \text{RMI}_{B,D}(U) = 0$. We obtain $Sig(a, B, D) = 0$.

Corollary 1 shows if features B have enough information to predict D, any new feature cannot increase the MI. Thus, the feature of significance zero can be removed from the system. This way, the redundant or irrelevant features are reduced.

We can compute crisp or fuzzy ordinal relations from numerical features. If crisp relations are used, we call the MI as RMI, while if fuzzy ordinal relations are considered, we call it FRMI.

B. Min-Redundancy-and-Max-Relevance Feature Search

The aforementioned analysis introduced a feature evaluation metric for monotonic classification. Now, we consider selecting features based on this metric.

A straightforward way is to exhaustively calculate the quality of feature subsets to find an optimal subset. However, this is not feasible even given a moderate size of candidate features because of the exponential complexity.

Some efficient algorithms were developed to overcome this problem. Battiti [28], and Peng *et al*. [29] discussed two criteria, which are called max-relevance (MR) and mRMR, respectively. Intuitively, features of larger relevance with decision should provide more information for classification. Therefore, the best feature should be the one of the largest MI. This strategy is called maximal relevance criterion (MR). Formally, MR criterion can be written as the following formulation:

$$\max \Upsilon, \Upsilon = \frac{1}{|B|} \sum_{a_i \in B} \text{RMI}_{a_i, D}. \tag{14}$$

In essence, the MR criterion is a feature selection algorithm based on ranking. We rank the features in the descending order according to the RMI between single feature and decision and then select the first *k* features, where *k* is specified in advance. It is well known that the ranking-based algorithms cannot remove redundancy between features because this algorithm neglects the relevance between input variables. Sometimes, the redundancy between features is so great that deleting some of them does not reduce the classification information of the original data. In this case, we should select a subset of features with the minimal redundancy condition. That is

$$\min(\Theta), \Theta = \frac{1}{|B|^2} \sum_{a_i, a_j \in B} \text{RMI}_{a_i, a_j}. \tag{15}$$

Then, we get a new criterion max $\Phi(D, R)$, which is called mRMR, by combining the two constraints:

$$\Phi = \frac{1}{|B|} \sum_{a_i \in B} \text{RMI}_{a_i, D} - \frac{\beta}{|B|^2} \sum_{a_i, a_j \in B} \text{RMI}_{a_i, a_j} \tag{16}$$

where the parameter β is used to regulate the relative importance of the MI between features and decision.

In [29], an incremental version of mRMR was developed. If a subset B of $l-1$ features has been selected in current step, now we select the lth feature. The incremental algorithm computes the following metric: $\forall a_j \in A - B$,

$$Sig(a_j, B, D) = \text{RMI}_{a_j, D} - \frac{\beta}{l-1} \sum_{a_i \in B} \text{RMI}_{a_i, a_j}. \tag{17}$$

The feature a maximizing $Sig(a; B, D)$ is selected.

mRMR calculates the significance of each feature one by one, and finally, we get the rank of the features. Then, some classification algorithm should be introduced to check the best k features with respect to the classification performance via cross validation.

In the incremental algorithm, we should compute the MI between the remaining $m-(l-1)$ features and decision attribute. Moreover, we also require calculating the MI between the remaining $m-(l-1)$ and the selected $l-1$ features. Thus, the total computational cost is $m-(l-1)+(m-(l-1)) \times (l-1) = (m-l+1) \times l$ in this step. In fact, this algorithm just uses the MI between features pairs, as well as the MI between features and decision. Therefore, we can compute and store the matrix of MI M_{ij} in advance, where M_{ij} is the MI between feature pairs. In this case, the total computational cost is $m + m \times m$, where m computes MI between *m* single features and decision, while $m \times m$ computes MI between feature pairs.

TABLE I
DATA DESCRIPTION

Data set	Instances	Features	Classes
Adult	48842	14	2
Ailerons	13750	41	3
Auto MPG	398	8	3
Australian Credit	690	15	2
Bankruptcyrisk	36	12	3
Cardiotocography	2126	21	3
Credit Approval	690	14	2
Fault	540	52	5
German Credit	1000	20	2
Housing	506	13	4
Pasture	36	22	3
Triazines	186	61	3
Windsor Housing	546	11	4
Wine Quality-red	1599	11	6

V. EXPERIMENTAL ANALYSIS

In this section, we present some experiments on real-world tasks to test the proposed technique. We compare our metrics with the dependence functions that are defined in dominance rough sets and fuzzy preference rough sets to show the robustness of RMI. We also compare RMI with MI and fuzzy mutual information (FMI) to show the effectiveness of these metrics in measuring monotonic consistency.

We introduce two monotonic classifiers, i.e., OLM [12] and OSDL [4], [23], to calculate the classification performance of the selected features. These algorithms are now implemented in Weka [51].

Here, mean absolute error (MAE) is introduced to evaluate decision performance, which is computed as

$$\text{MAE} = \frac{1}{N} \sum\nolimits_{i=1}^{N} |\hat{y}_i - y_i| \tag{18}$$

where N is the number of samples in the test set, $\widehat{y_i}$ is the output of the algorithm, and y_i is the real output of the ith sample. Moreover, we also compute the classification error rate (CE) of models.

Fourteen monotonic tasks are collected from the University of California, Irvine, machine learning repository and other webpages [57]. The detailed information about these datasets is given in Table I.

We randomly select three tasks, including Adult, Pasture, and Wine Quality-red, to test the robustness of RMI and monotonic

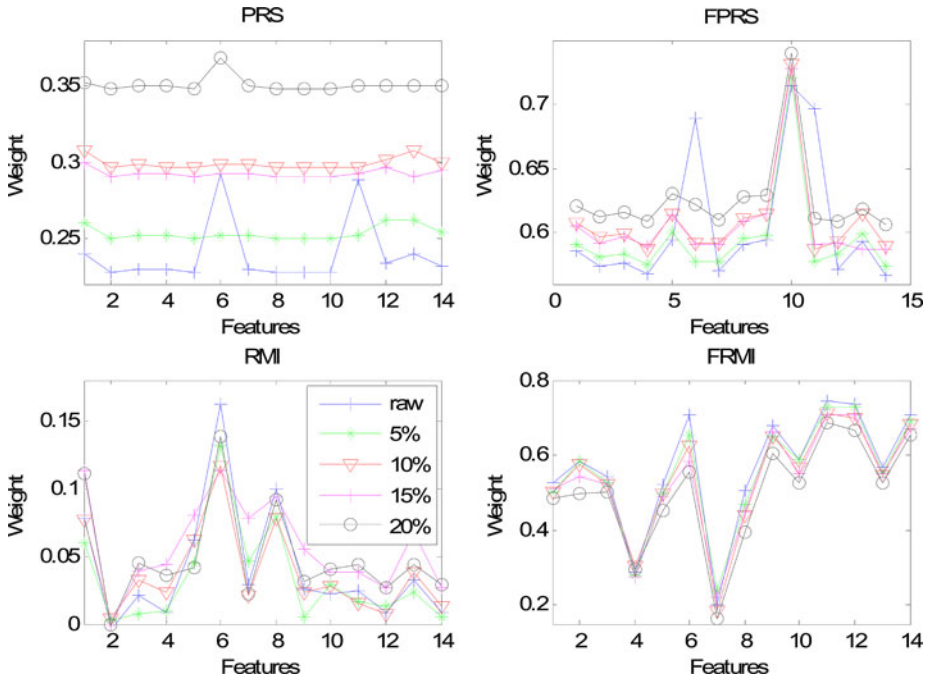

Fig. 5. Metric of monotonic consistency computed at different noise levels (Adult).

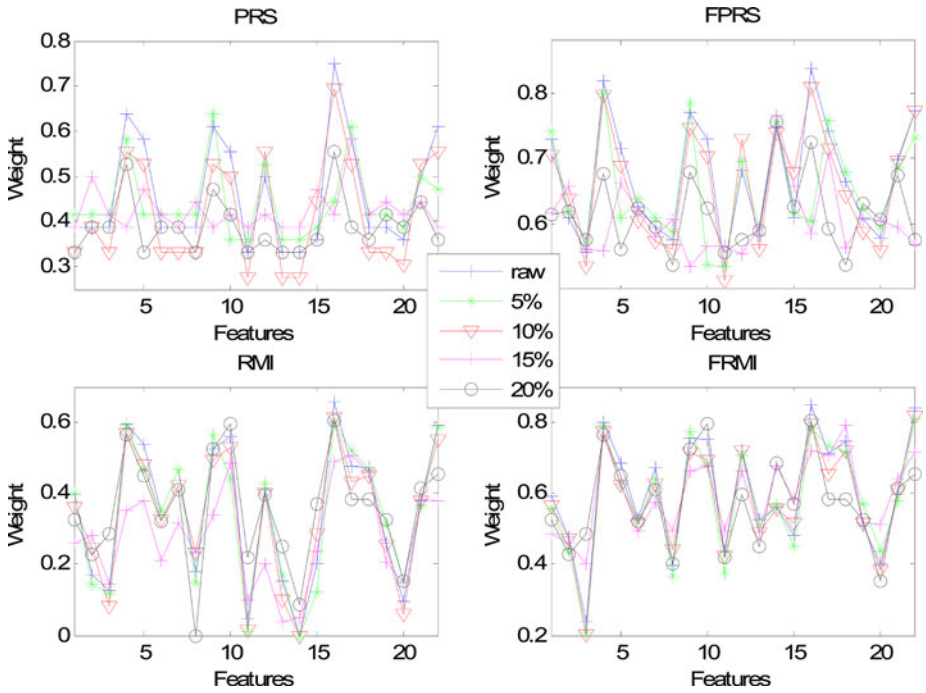

Fig. 6. Metric of monotonic consistency computed at different noise levels (Pasture).

dependence that is defined in dominance rough sets and fuzzy preference rough sets. We calculate dependence or MI between decision and each single feature based on the raw datasets. Moreover, we randomly draw $k\%(k = 5, 10, 15, \text{and } 20)$ samples from the raw datasets and replace their class labels with arbitrary candidates. These samples are considered to be class noisy and are put back to the raw datasets. Now, we observe the variation of dependence or MI.

If the metric is robust, we expect that the value variation of metric will be small. Thus, the difference of metrics that are computed at different levels of noise would be small enough. Monotonic dependence (PRS), monotonic fuzzy dependence (FPRS), RMI, and FRMI computed with the raw datasets and noisy datasets are shown in Figs. 5– 7.

Observing the curves Fig. 5, we see that PRS changes a lot at different levels of noise. The metric values are completely different from the value that is computed with the raw dataset when

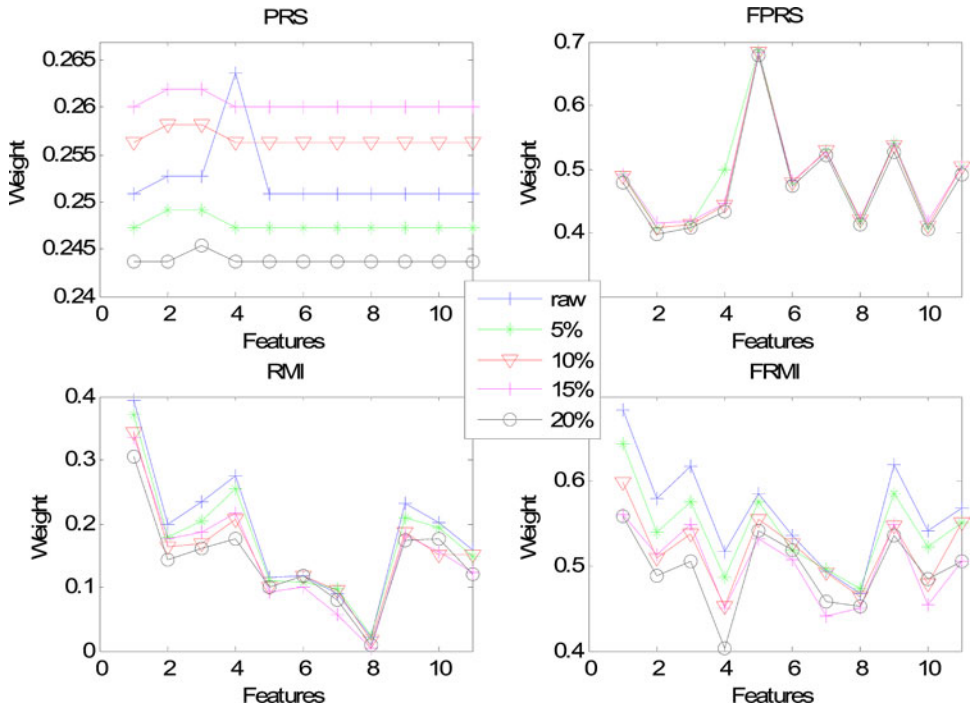

Fig. 7. Metric of monotonic consistency computed at different noise levels (Wine Quality-red).

5% noisy samples are added in Adult. As to FPRS, although the metric values also vary, it seems that this metric is more robust than PRS. RMI and FRMI are far more robust than PRS and FPRS as the metric values are stable when noisy samples are added. The same conclusions can also be drawn from Figs. 6 and 7.

Now, we compare the classification performance of different feature subsets that are selected with six metric functions: MI, FMI, RMI, FRMI, PRS, and FPRS. We rank the features with the descending order of these metric values and added the top features one by one. In this process, we compute the classification performances of the corresponding features based on fivefold cross validation. Two metrics of classification performance are calculated: CE and MAE. The best classification performance and the number of the corresponding subsets of features are given in Tables II and III, where raw is the performance of the raw datasets. Because of the limitation of space, here, we just give the average performance of cross validation in these tables.

We first compare the performances that are computed before and after feature selection. We see that both the CE and MAE decrease after some features are reduced from the raw datasets. As to some tasks like Bankruptcyrisk and Cardiotocography, feature selection significantly improves the classification.

RMI, FRMI, PRS, and FPRS are the evaluation functions that consider the ordinal structures of features and decision, while MI and FMI do not reflect the monotonic consistency. We can see that most tasks produce the better classification performances after attribute reduction based on RMI, FRMI, PRS, and FPRS as to OLM and OSDL. Although MI and FMI show good performances in feature evaluation for general classification tasks, they are worse than RMI and FRMI and even worse than PRS and FPRS. In addition, RMI and FRMI are better than PRS and FPRS in most cases.

Figs. 8 and 9 present the curves of error rate that varies with the number of the selected features. We consider six tasks in these figures. As to OLM, the CEs decrease when the first several features are used, and then, the error rates increase after they arrive at their minimums. This trend is the same as those in feature selection for general classification tasks [58], [59]. The first several features are useful for classification learning. However, too many selected features may lead to the issue of overfitting. Thus, a proper number of features are very important to obtain good classification performance.

As to OSDL, no consistent rule can be drawn from these curves. Although feature reduction improves classification performance of OSDL, these error rates do not decrease with the addition of new features. It is easy to select the best features for OSDL.

Rank-based feature selection does not consider the redundant information between the selected features, which may result in superfluous features. The strategy of mRMR consider not only the relevance between decision and features but the relevance between features as well. The features high relevant to decision and low correlated with the selected features are considered to be useful.

Now, we compare the features that are selected with mRMR strategy, where MI, FMI, RMI, and FRMI are all employed to evaluate the candidate features. As mentioned earlier, mRMR just outputs a rank of candidate features. We should introduce other classification algorithms to validate the feature subsets. Here, we also consider OLM and OSDL. The performances of the best subsets of features are given in Table IV.

TABLE II
OLM PERFORMANCE OF THE SUBSETS OF FEATURES SELECTED WITH DIFFERENT EVALUATION FUNCTIONS (%)

Data set		MI	RMI	FMI	FRMI	PRS	FPRS	raw
Adult	CE	25.0±1.6(12)	25.0±1.6(3)	26.8±3.0(8)	25.6±2.9(14)	28.6±4.0(13)	25.6±2.9(10)	28.6±4.8
	MAE	25.0±1.6(12)	25.0±1.6(3)	26.8±3.0(8)	25.6±2.9(14)	28.6±4.0(13)	25.6±2.9(10)	28.6±4.8
Ailerons	CE	53.3±3.5(2)	37.0±3.8(19)	55.2±5.0(4)	36.9±3.9(14)	36.3±3.4(37)	32.7±3.0(15)	61.9±7.7
	MAE	35.6±5.3(2)	24.7±3.1(19)	36.8±4.5(4)	24.6±4.5(14)	24.2±4.9(37)	21.8±3.2(15)	41.3±13.9
Auto MPG	CE	29.3±4.0 (5)	28.6±3.1(5)	28.6±3.1(5)	28.6±3.1(5)	28.6±3.1(5)	28.3±2.8(7)	32.0±5.1
	MAE	19.6±7.0(5)	19.1±4.6(5)	19.1±4.6(5)	19.1±4.6(5)	18.9±4.6(7)	17.0±6.5(4)	22.0±6.8
Australian Credit	CE	16.5±4.9(6)	16.5±4.9(6)	17.0±4.9(11)	15.1±3.5(5)	17.1±1.4(10)	17.1 ±1.4(10)	23.6±2.8
	MAE	16.5±4.9(6)	16.5±4.9(6)	17.0±4.9(11)	15.1±3.5(5)	17.1±1.4(10)	17.1 ±1.4(10)	23.6±2.8
Bankruptcyrisk	CE	17.9 ±6.6(2)	17.9±6.6(2)	17.9±6.6(2)	17.9±6.6(2)	17.9±6.6(2)	17.9±6.6(2)	51.3±18.0
	MAE	12.0±6.6(2)	12.0±6.6(2)	12.0±6.6(2)	12.0±6.6(2)	12.0±6.6(2)	12.0±6.6(2)	34.2±18.0
Cardiotocography	CE	10.8±0.7(12)	10.5±1.1(16)	10.6±1.3(17)	10.5±1.1(16)	11.9±2.9(12)	10.6±1.2(15)	12.3±0.64
	MAE	7.2±0.4(12)	7.0±1.6(16)	7.1±1.7(17)	7.0±1.6(16)	7.9±3.2(12)	7.1±1.4(15)	8.2±1.4
Credit Approval	CE	17.0±3.6(6)	11.3±2.2(3)	17.4±4.0(7)	11.2±2.2(1)	20.3±2.6(12)	19.0±4.3(10)	25.8±6.1
	MAE	17.0±3.6(6)	11.3±2.2(3)	17.4±4.0(7)	11.2±2.2(1)	20.3±2.6(12)	19.0±4.3(10)	25.8±6.1
Fault	CE	3.7±2.2(49)	3.7±2.2(49)	3.7±2.2(47)	3.5±2.0(49)	3.3±1.9(44)	3.7±1.9(51)	3.9±1.8
	MAE	1.5±5.8(49)	1.5±5.8(49)	1.5±6.5(47)	1.4±5.7(49)	1.3±5.7(44)	1.5±5.3(51)	1.6±5.2
German Credit	CE	30.0±0.0(1)	29.0±1.9(4)	30.0±0.0(1)	27.8±2.6(7)	30.0±0.0(1)	29.9±0.0(1)	36.0±3.0
	MAE	30.0±0.0(1)	29.0±1.9(4)	30.0±0.0(1)	27.8±2.6(7)	30.0±0.0(1)	29.9±0.0(1)	36.0±3.0
Housing	CE	32.4±3.3(12)	32.2±2.7(10)	33.0±2.6(6)	33.0±3.6(10)	32.2±2.7(10)	33.8±3.7(12)	35.4±4.4
	MAE	16.2±5.1(12)	16.1±6.5(10)	16.5±4.0(10)	16.5±4.7(10)	16.1±4.4(10)	16.9±5.5(12)	17.7±7.3
Pasture	CE	11.1±10.7(2)	13.9±10.7(11)	11.2±10.7(2)	11.1±10.7(2)	16.7±13.5(4)	16.7±13.5(4)	22.2±8.3
	MAE	7.4±10.7(2)	9.3±0.8(11)	7.4±10.7(2)	7.4±10.7(2)	11.1±13.5(4)	11.1±13.5(4)	14.8±12.4
Triazines	CE	55.4±1.9(2)	50.0±3.3(2)	54.8±5.7(5)	51.6±11.9(45)	45.7±10.5(25)	51.1±7.8(26)	61.3±9.0
	MAE	36.9±8.2(2)	33.3±4.3(2)	36.6±11.1(5)	34.4±17.3(45)	30.5±11.6(25)	34.1±10.6(26)	40.9±17.1
Windsor Housing	CE	48.2±6.6(10)	47.4±7.3(10)	48.2±6.6(10)	47.4±6.3(11)	48.4±8.1(11)	46.7±8.1(9)	49.1±7.2
	MAE	24.1±9.0(10)	23.7±9.2(10)	24.1±9.0(10)	23.7±7.6 (11)	24.2±9.5(11)	23.4±10.3(11)	25.5±9.0
Wine Quality-red	CE	47.5±2.6(1)	47.5±2.6(1)	47.0±2.7(7)	47.5±2.6(1)	51.2±2.2(11)	50.4±3.0(6)	52.6±2.7
	MAE	15.8±2.3(1)	15.8±2.3(1)	15.7±3.5(7)	15.8±2.3(1)	17.1±2.7(11)	16.8±3.7(6)	17.5±5.2

TABLE III
OSDL PERFORMANCE OF SUBSETS OF FEATURES SELECTED WITH DIFFERENT EVALUATION FUNCTIONS (%)

Data set		MI	RMI	FMI	FRMI	PRS	FPRS	raw
Adult	CE	22.8±0.5(1)	21.6±3.3(3)	22.8±0.5(1)	21.6±3.3(3)	22.8±0.5(1)	22.8±0.5(1)	26.6±2.1
	MAE	22.8±0.5(1)	21.6±3.3(3)	22.8±0.5(1)	21.6±3.3(3)	22.8±0.5(1)	22.8±0.5(1)	26.6±2.1
Ailerons	CE	39.1±2.6(1)	33.0±4.2(4)	39.1±2.6(1)	32.6±4.2(4)	33.4±4.4(38)	32.7±5.5(15)	54.1±7.5
	MAE	26.1±2.9(1)	22.0±4.8(4)	26.1±2.9(1)	21.7±4.8(4)	22.3±4.5(38)	21.8±5.8(15)	36.1±7.7
Auto MPG	CE	25.3±2.4(2)	24.8±3.2(4)	27.0±2.9(4)	27.0±2.9(3)	27.0±2.4(4)	25.5±2.4(3)	33.9±1.4
	MAE	16.8±3.7(2)	16.2±3.1(4)	18.0±3.5(4)	18.0±3.9(3)	18.0±3.6(4)	17.0±3.6(4)	22.6±4.0
Australian Credit	CE	14.4±3.9(6)	14.4±3.9(6)	14.4±3.9(6)	13.5±3.5(1)	20.3±3.3(12)	0.1±0.3(3)	20.3±4.1
	MAE	14.4±3.9(6)	14.4±3.9(6)	14.4±3.9(6)	13.5±3.5(1)	20.3±3.3(12)	0.1±0.3(3)	20.3±4.1
Bankruptcyrisk	CE	12.8±13.5(6)	7.7±11.4(3)	12.8±13.5(6)	7.7±11.4(3)	10.3±10.6(6)	7.7±11.4(3)	30.8±10.9
	MAE	8.6±13.5(6)	5.1±11.4(3)	8.6±13.5(6)	5.1±11.4(3)	6.8±10.6(6)	5.1±11.4(3)	20.5±10.9
Cardiotocography	CE	13.5±1.7(3)	12.2±1.0(4)	12.1±1.8(3)	10.9±1.7(4)	11.1±4.8(4)	10.6±1.2(15)	27.8±2.6
	MAE	9.0±2.1(3)	8.2±1.4(4)	8.1±2.3(3)	7.2±2.1(4)	7.4±5.0(4)	7.1±1.4(15)	18.5±2.7
Credit Approval	CE	11.9±2.2(1)	11.9±2.2(1)	11.9±2.2(1)	11.9±2.2(1)	13.5±0.7(9)	11.9±2.2(1)	26.4±4.3
	MAE	11.9±2.2(1)	11.9±2.2(1)	11.9±2.2(1)	11.9±2.2(1)	13.5±0.7(9)	11.9±2.2(1)	26.4±4.3
Fault	CE	36.5±3.9(17)	36.5±3.9(17)	38.5±6.0(21)	37.4±2.7(18)	42.6±5.2(27)	43.7±3.0(32)	63.0±2.9
	MAE	14.6±4.6(17)	14.6±4.6(17)	15.4±9.0(21)	15.0±4.9(18)	17.0±7.0(27)	17.5±1.8(32)	25.2±5.9
German Credit	CE	28.3±1.4(1)	28.1±1.6(4)	28.3±1.4(1)	28.1±1.6(6)	30.0±0.0(1)	29.5±0.8(5)	50.5±2.2
	MAE	28.3±1.4(1)	28.1±1.6(4)	28.3±1.4(1)	28.1±1.6(6)	30.0±0.0(1)	29.5±0.8(5)	50.5±2.2
Housing	CE	31.2±4.4(7)	32.4±3.9(9)	32.2±3.7(7)	34.0±3.3(10)	33.4±3.9(4)	34.0±3.3(12)	36.0±3.1
	MAE	15.6±5.8(7)	16.2±4.1(9)	16.1±3.3(7)	17.0±2.7(10)	16.7±4.7(4)	17.0±2.0(12)	18.0±2.2
Pasture	CE	25.0±10.1(1)	19.4±13.0(5)	25.0±10.1(2)	22.2±14.8(4)	19.4±8.2(5)	19.4±8.2(6)	63.9±12.4
	MAE	16.7±10.1(1)	13.0±13.0(5)	16.7±10.1(2)	14.8±14.8(4)	13.0±8.2(5)	13.0±8.2(6)	42.6±12.4
Triazines	CE	51.6±7.4(30)	48.4±4.1(33)	55.9±6.7(13)	46.8±9.9(34)	45.7±5.8(22)	49.5±4.9(60)	55.9±4.9
	MAE	34.4±10.1(30)	32.3±5.2(33)	37.3±10.1(13)	31.2±15.2(34)	30.5±7.1(22)	33.0±5.5(60)	37.3±5.5
Windsor Housing	CE	45.1±7.1(11)	45.1±7.1(11)	45.1±7.1(11)	45.1±7.1(11)	45.1±7.1(11)	42.9±6.8(9)	45.1±7.1
	MAE	22.5±8.1(11)	22.5±8.1(11)	22.5±8.1(11)	22.5±8.1(11)	22.5±8.1(11)	21.4±8.5(9)	22.5±8.1
Wine Quality-red	CE	46.4±1.1(11)	43.9±1.0(2)	48.2±3.9(3)	44.2±1.6(2)	47.2±3.2(2)	44.6±1.1(5)	55.3±3.2
	MAE	15.5±1.2(1)	14.6±1.6(2)	16.1±4.5(3)	14.7±2.1(2)	15.7±3.4(2)	14.9±1.5(5)	18.5±6.0

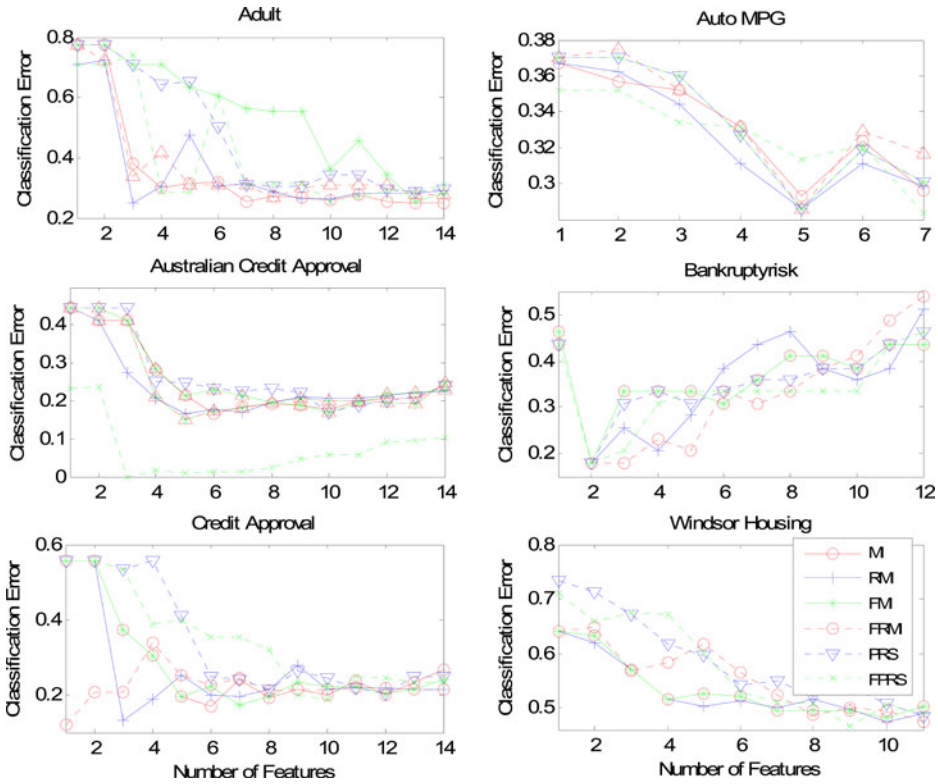

Fig. 8. OLM performance curves with number of features.

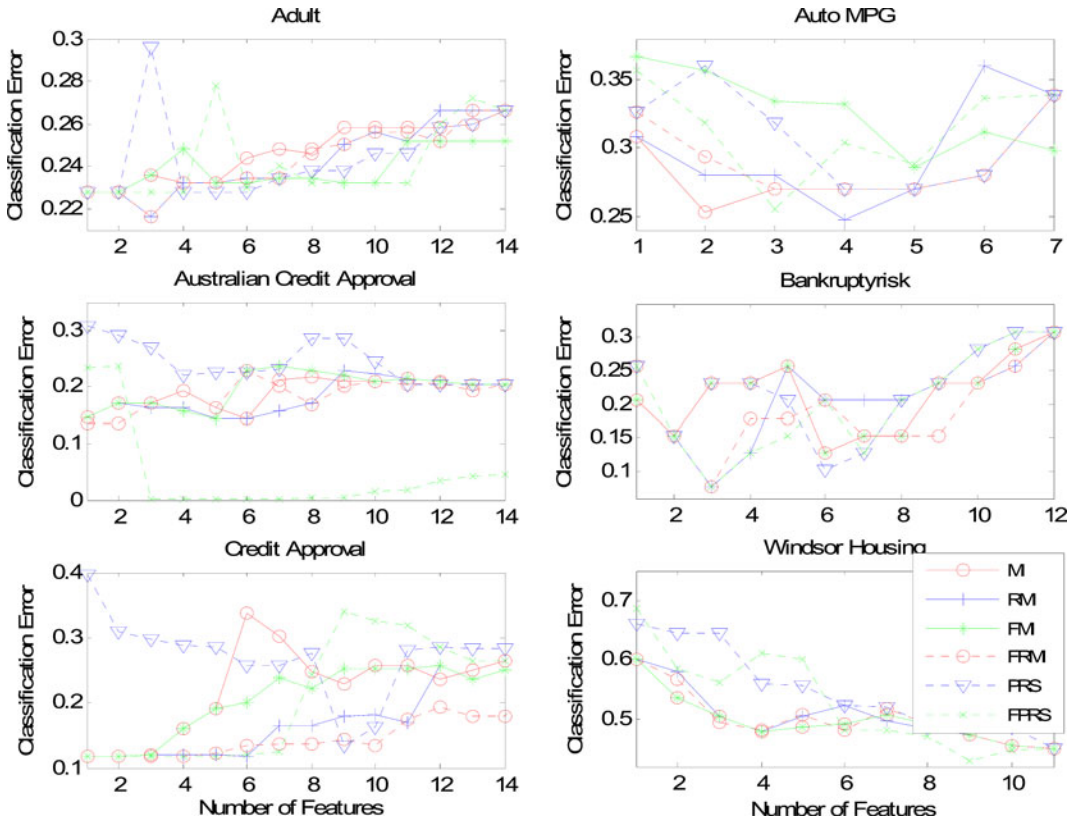

Fig. 9. OSDL performance curves with number of features.

TABLE IV
MRMR-BASED FEATURE SELECTION, WHERE FEATURES ARE EVALUATED WITH MI, FMI, RMI, AND FRMI (%)

Data set		OLM				OSDL			
		MI	RMI	FMI	FRMI	MI	RMI	FMI	FRMI
Adult	CE	29.6±3.8(14)	28.6±6.4(13)	30.8±3.8(14)	29.8±8.3(12)	22.8±0.6(1)	22.8±0.6(1)	22.8±0.6(1)	22.8±0.6(1)
	MAE	29.6±3.8(14)	28.6±6.4(13)	30.8±3.8(14)	29.8±8.3(12)	22.8±0.6(1)	22.8±0.6(1)	22.8±0.6(1)	22.8±0.6(1)
Ailerons	CE	53.7±3.2(4)	35.8±1.5(17)	55.2±5.9(4)	36.6±3.9(15)	39.1±2.6(1)	31.4±5.0(12)	39.1±5.0(1)	31.6±4.7(4)
	MAE	35.8±3.6(4)	23.9±1.9(17)	36.8±7.3(4)	24.4±3.3(15)	26.1±2.9(1)	20.1±5.2(12)	26.1±5.2(1)	21.1±5.0(4)
Auto MPG	CE	29.1±2.5(7)	28.6±4.2(7)	29.3±3.1(7)	28.8±1.3(7)	28.8±5.1(5)	28.6±3.1(5)	30.9±3.7(1)	28.1±4.3(6)
	MAE	17.4±6.3(7)	19.1±5.2(7)	19.6±3.0(7)	19.2±1.9(4)	19.5±10.4(1)	19.1±4.3(5)	20.6±4.5(1)	18.7±4.4(6)
Australian Credit	CE	19.0±2.7(7)	16.5±3.5(5)	19.0±2.7(7)	17.5±3.6(5)	14.5±3.2(1)	14.1±3.7(5)	14.2±3.4(3)	14.1±3.7(5)
	MAE	19.0±2.7(7)	16.5±3.5(5)	19.0±2.7(7)	17.5±3.6(5)	14.5±3.2(1)	14.1±3.7(5)	14.2±3.4(3)	14.1±3.7(5)
Bankruptcyrisk	CE	17.9±6.6(2)	17.9±6.6(2)	17.9±6.6(2)	17.9±6.6(2)	7.7±7.2(4)	7.7±7.2(4)	7.7±7.2(4)	7.7±7.2(4)
	MAE	12.0±6.6(2)	12.0±6.6(2)	12.0±6.6(2)	12.0±6.6(2)	5.1±7.2(4)	5.1±7.2(4)	5.1±7.2(4)	5.1±7.2(4)
Cardiotocography	CE	10.8±1.2(15)	10.2±1.8(15)	11.0±1.3(18)	10.7±1.4(10)	17.8±1.1(4)	16.4±0.7(2)	10.9±1.3(8)	10.5±2.8(2)
	MAE	7.2±1.7(15)	6.8±2.4(15)	7.3±1.2(18)	7.2±1.6(10)	11.9±1.5(4)	10.9±1.0(2)	7.3±1.4(8)	7.0±2.7(2)
Credit Approval	CE	18.7±2.5(6)	18.6±1.2(12)	21.0±4.0(13)	21.0±2.3(19)	11.9±2.2(1)	11.7±2.3(3)	11.9±2.2(1)	11.7±2.3(3)
	MAE	18.7±2.5(6)	18.6±1.2(12)	21.0±4.0(13)	21.0±2.3(19)	11.9±2.2(1)	11.7±2.3(3)	11.9±2.2(1)	11.7±2.3(3)
Fault	CE	10.4±2.7(51)	3.9±1.8(50)	3.7±2.0(49)	3.5±1.8(49)	36.7±4.6(9)	25.9±4.6(7)	38.3±5.3(12)	37.4±3.2(18)
	MAE	4.2±7.5(51)	1.6±4.6(50)	1.5±5.2(49)	1.4±5.1(49)	14.7±6.9(9)	10.4±6.5(7)	15.3±6.3(12)	15.0±4.9(18)
German Credit	CE	29.9±0.22(3)	29.2±2.4(5)	29.8±2.2(7)	28.2±2.0(6)	29.8±2.2(4)	28.4±1.7(4)	30.0±0.0(1)	28.1±3.3(5)
	MAE	29.9±0.22(3)	29.2±2.4(5)	29.8±2.2(7)	28.2±2.0(6)	29.8±2.2(4)	28.4±1.7(4)	30.0±0.0(1)	28.1±3.3(5)
Housing	CE	32.8±3.8(13)	30.4±4.4(7)	35.0±6.1(13)	33.2±2.0(9)	34.0±5.5(8)	33.4±4.6(8)	36.0±3.1(13)	34.4±2.9(9)
	MAE	16.4±6.7(13)	15.2±6.4(7)	17.5±8.5(13)	16.6±4.1(9)	17.0±4.8(8)	16.7±4.8(8)	18.0±2.2(13)	17.2±3.0(9)
Pasture	CE	22.2±7.3(5)	16.712.1(3)	27.8±10.2(5)	16.7±23.5(3)	22.2±16.3(4)	16.7±23.5(3)	22.2±16.3(4)	16.7±23.5(3)
	MAE	14.8±6.2(5)	11.1±12.1(3)	18.5±16.7(5)	11.1±23.5(3)	14.8±16.3(4)	11.1±23.5(3)	14.8±16.3(4)	11.1±23.5(3)
Triazines	CE	53.2±7.0(32)	46.2±4.7(5)	51.1±4.4(3)	47.3±9.0(5)	51.1±4.7(27)	49.5±4.4(6)	51.6±10.2(9)	50.0±6.6(12)
	MAE	35.5±14.9(32)	30.1±6.4(5)	34.1±5.7(3)	31.5±16.3(5)	34.1±9.8(27)	33.0±6.5(6)	34.4±19.0(9)	33.3±7.7(12)
Windsor Housing	CE	49.9±8.2(11)	49.1±5.2(8)	49.9±8.2(11)	46.9±7.7(10)	45.1±7.1(11)	45.1±7.1(11)	45.1±7.1(11)	45.1±7.1(11)
	MAE	24.6±11.2(11)	24.5±7.4(8)	24.6±5.7(11)	23.4±10.7(10)	22.5±8.1(11)	22.5±8.1(11)	22.5±8.1(11)	22.5±8.1(11)
Wine Quality-red	CE	46.5±2.6(2)	50.5±3.0(2)	50.3±1.9(1)	47.7±3.4(2)	40.0±1.3(4)	40.0±1.3(4)	39.9±0.8(5)	39.1±2.8(6)
	MAE	15.5±2.2(2)	16.8±4.9(2)	16.8±2.2(11)	15.9±2.6(2)	13.3±1.1(4)	13.3±1.1(4)	13.3±0.9(5)	13.0±2.5(6)

Comparing the results in Table IV, we see that combination of RMI or FRMI with mRMR is much better than integration of MI or FMI with mRMR. Regarding OLM, RMI and FRMI are better than MI and FMI on 12 of 14 tasks. As to OSDL, RMI and FRMI outperform MI and FMI on 11 of 14 tasks, and they obtain the same performance on all the other datasets, which show RMI and FRMI are no worse than MI and FMI. In addition, as to OSDL, it is notable that FRMI-based mRMR obtains the best performances on nine of the tasks, which reflects that this attribute reduction algorithm is effective for OSDL.

VI. CONCLUSIONS AND FUTURE WORK

Monotonic classification is a class of special tasks in machine learning. Monotonicity constraints are considered as the fundamental assumption about these tasks. However, existing techniques for classification modeling are not applicable to this domain because they fail to discover and represent the ordinal structures of datasets. In this paper, we introduce a metric function, which is called RMI, to measure monotonic consistency between features and decision. We, then, combine this function with the mRMR search strategy to construct an effective feature selection algorithm for monotonic classification. Some numerical experiments are conducted to test the performance of the proposed algorithm. The following conclusions are drawn from the analysis.

First, although MI and FMI are effective and robust functions in measuring feature quality for general classification tasks, they are not applicable to monotonic tasks because they cannot reflect the ordinal structures.

Second, monotonic dependence functions that are defined in dominance rough sets and fuzzy preference rough sets are able to reflect the monotonic relevance between features and decision. However, these functions are very sensitive to noisy samples. It makes them not applicable in noisy conditions.

Finally, RMI and FRMI combine the advantages of MI and dominance rough sets. They are robust to noisy information and effective in reflecting ordinal structures. The proposed feature selection algorithms are competent with an MI-based mRMR algorithm in monotonic classification.

In this paper, we talk about classification tasks that make the assumption that all features are monotonic with decision. In real-world applications, this assumption may not be true. Sometimes, just some, instead of all, features have monotonic relations with decision. Those nonmonotonic features are also useful to construct accurate predicting models. In decision analysis, monotonic features are called criteria, while nonmonotonic features are called attributes. The corresponding task is called multicriteria and multiattribute decision analysis. No much attention has been paid to this problem so far. We will develop feature selection techniques for it in future.

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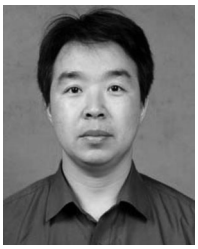

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